

# **Error Detector Placement for Soft Computation**



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# Soft Computing Applications

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- Applications in AI, multimedia processing...
- Expected to dominate future workloads [Dubey'07]

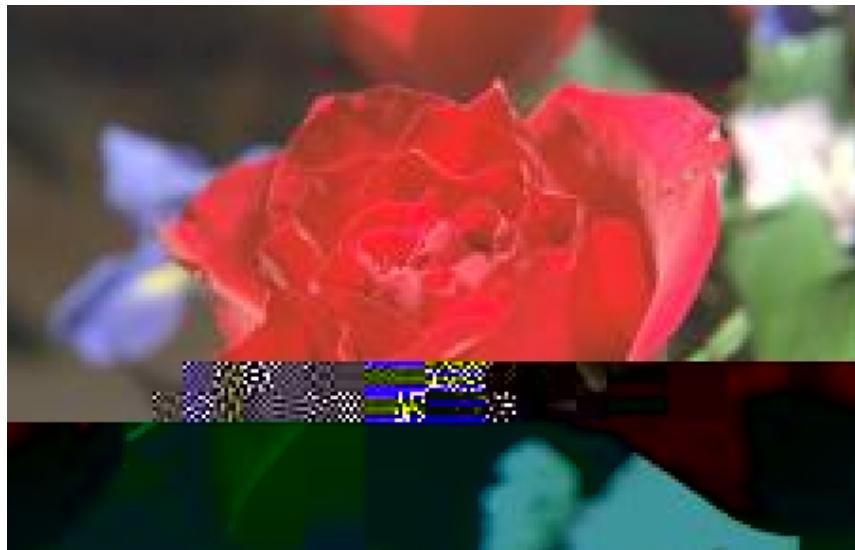


Original image (left) versus faulty image from JPEG decoder

# Egregious Data Corruptions

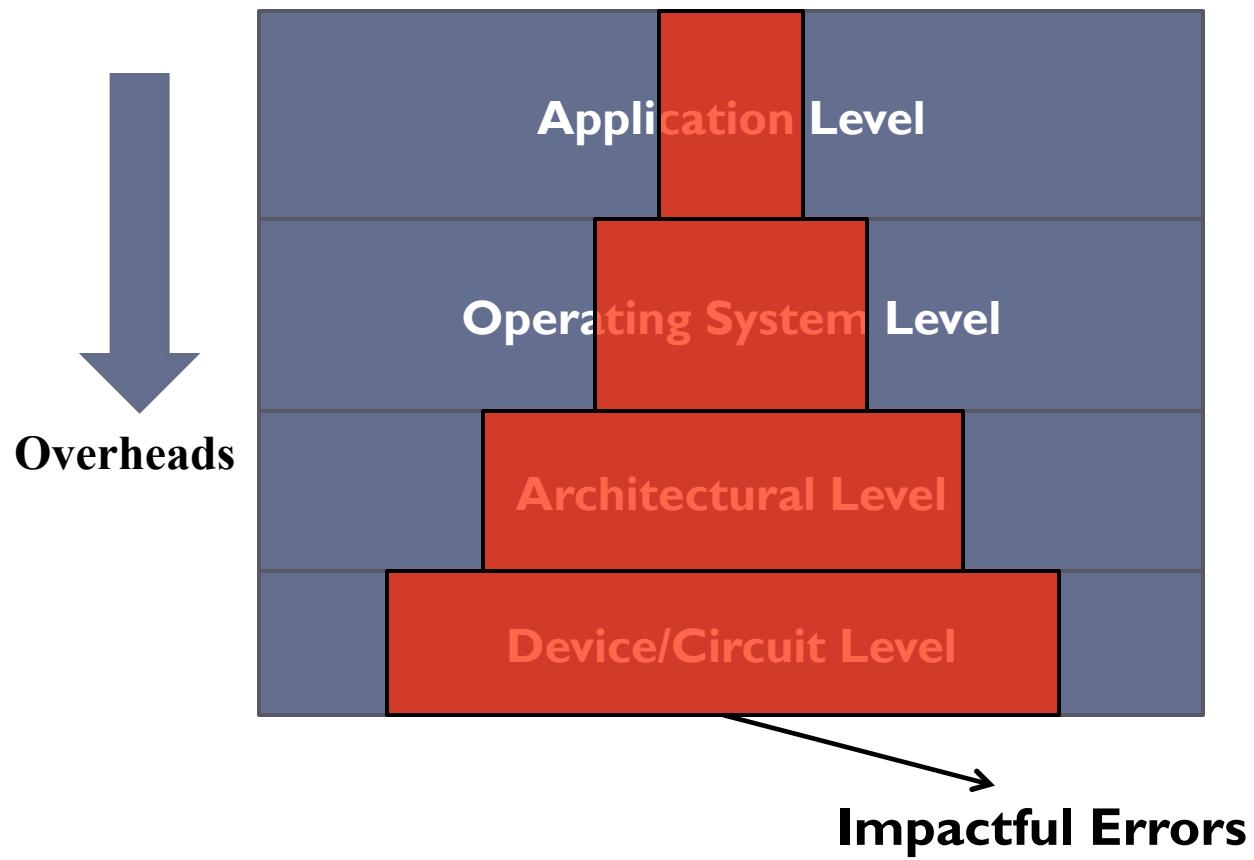
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- Large or unacceptable deviation in output
- Based on fidelity metric (e.g., PSNR)



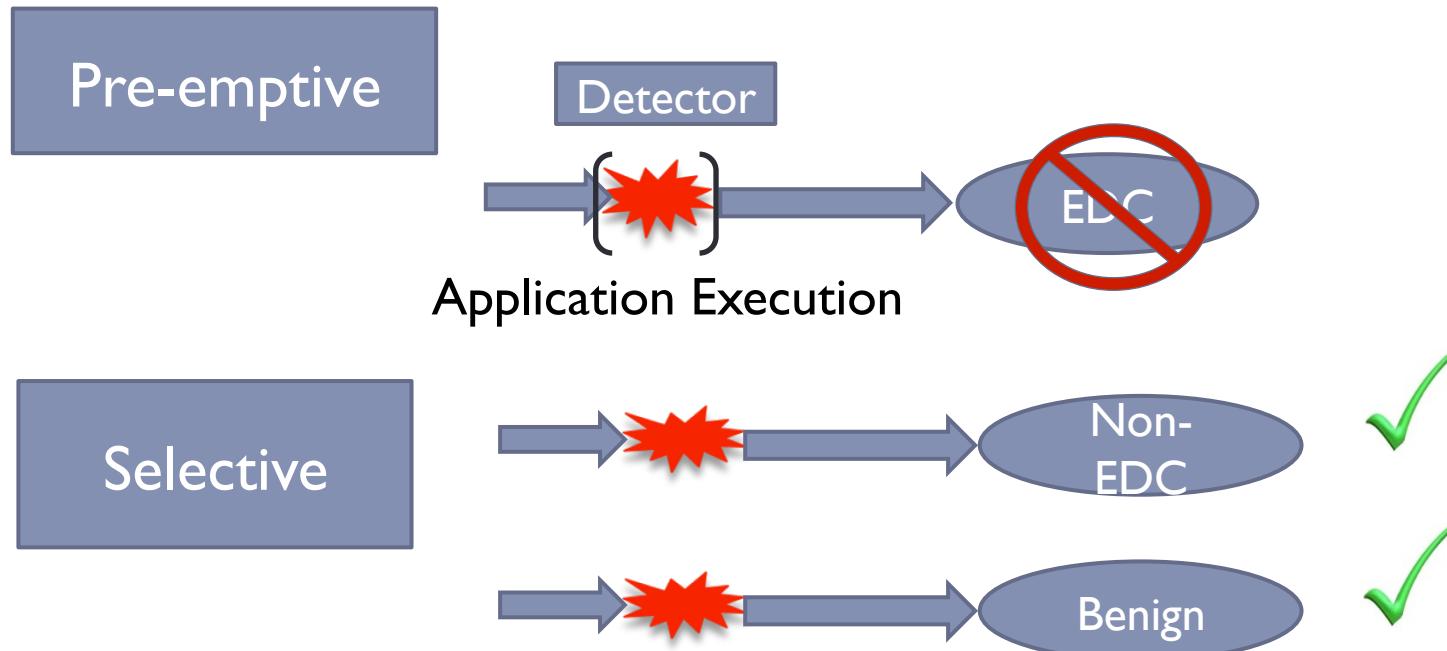
EDC image (PSNR of 11.37) of JPEG vs Non-EDC image (PSNR of 44.79)

# Why Software Solutions?



# Goal

- Detect EDC causing faults

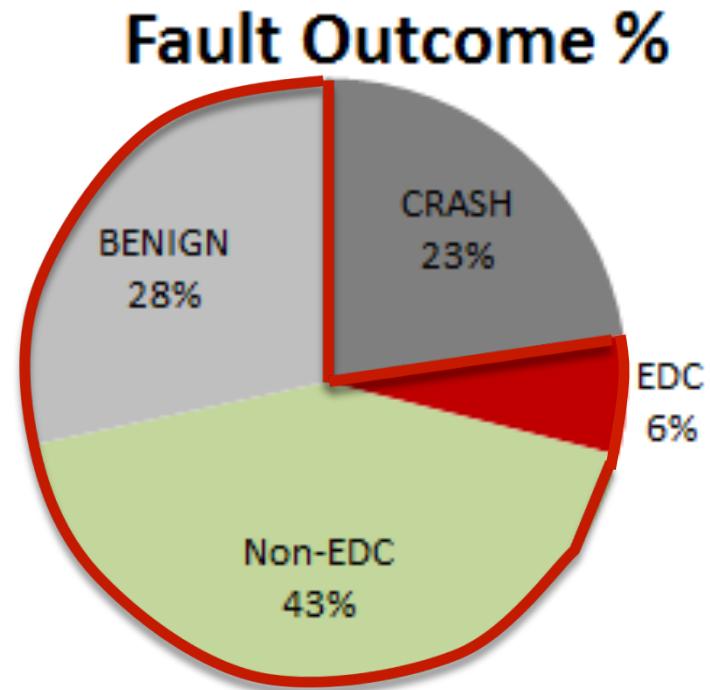


# Why detect EDC Causing Faults?

- Unacceptable outcome to the end user

- 92% : tolerable outcomes

Blindly detecting all faults is wasteful



# Outline

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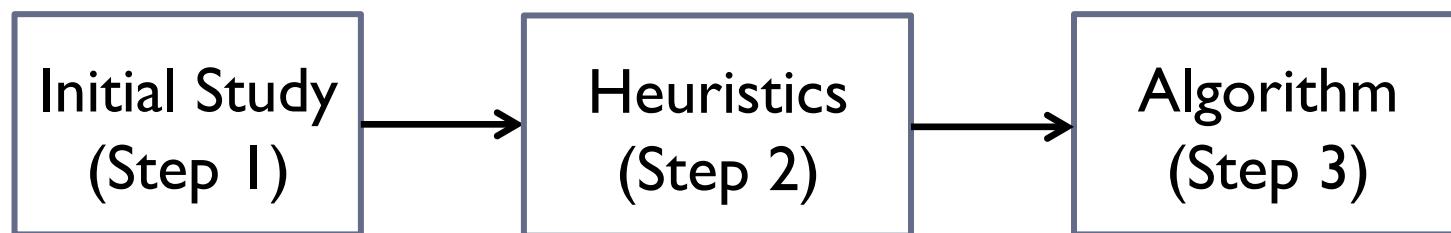
- ▶ Motivation
- ▶ Approach
- ▶ Experimental Setup and Results

- ▶ Conclusion

# Approach

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- Step 1: Separate EDCs from Non-EDCs by fault injections
- Step 2: Heuristics identifying code regions prone to EDC causing faults
- Step 3: Automated algorithm for detector placement

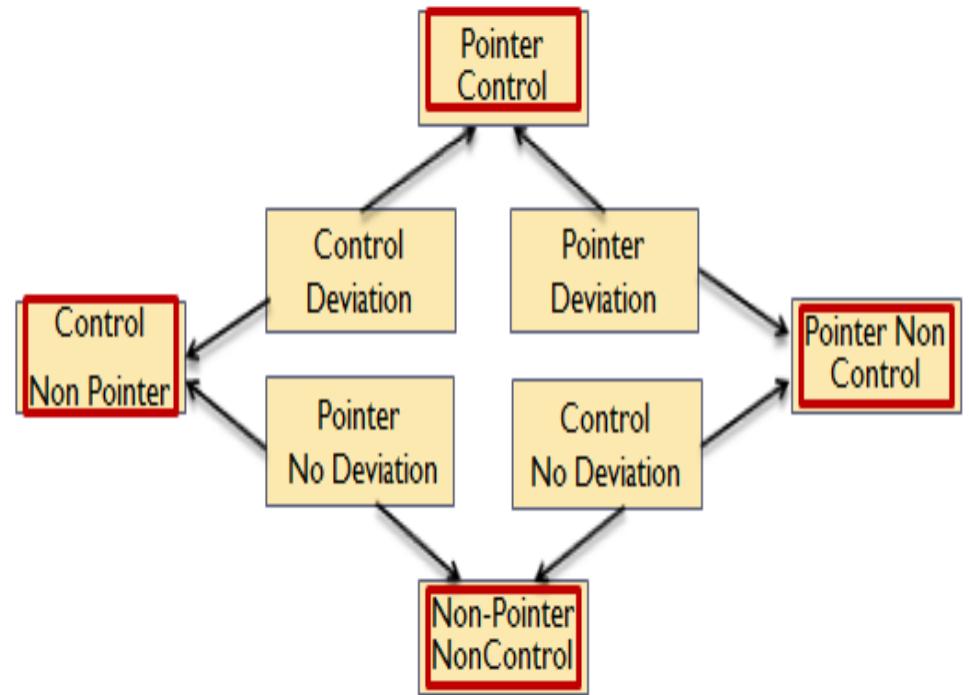


## Step 1: Initial Study

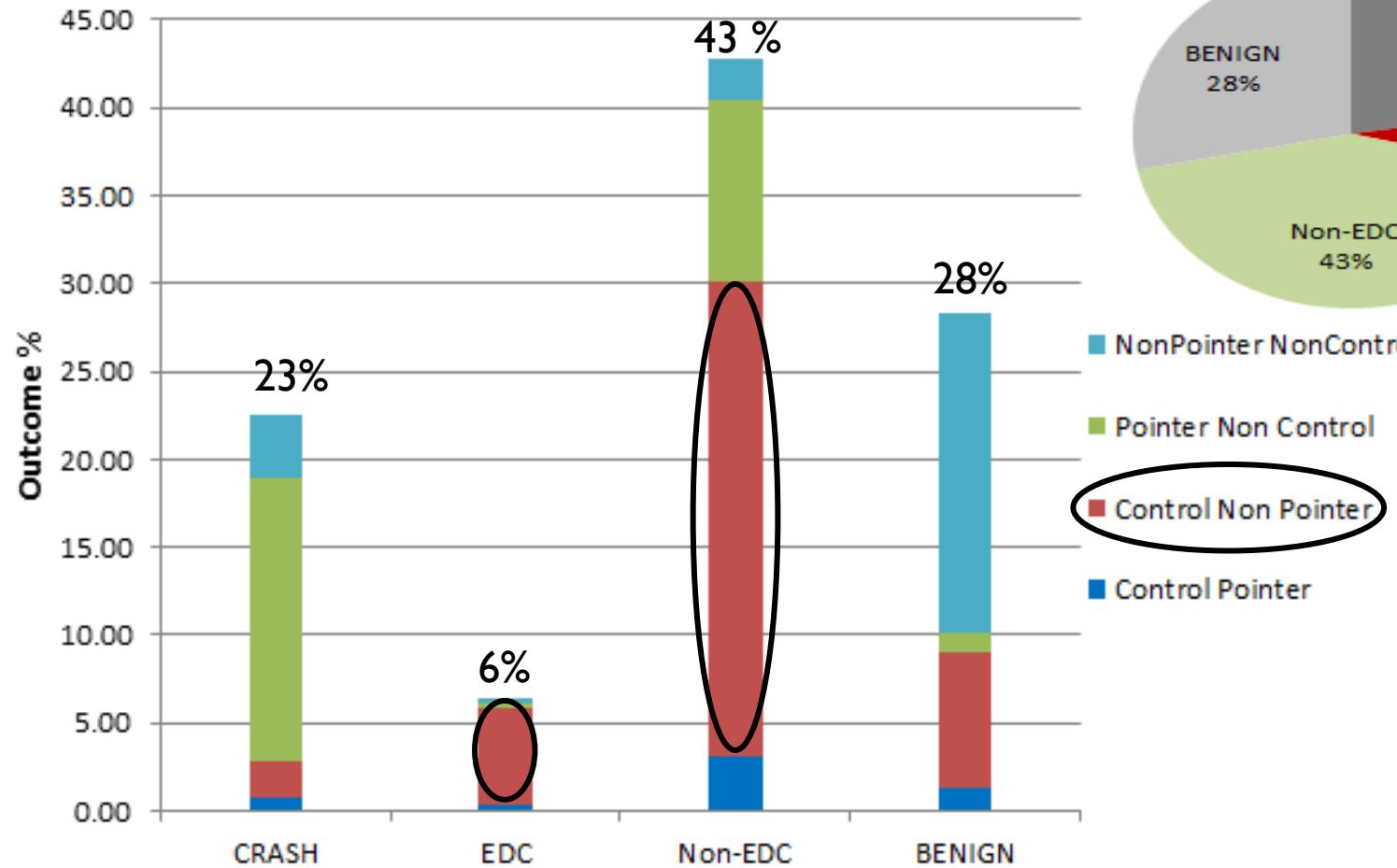
- Fault injection using LLFI [Thomas'13]
- Correlation between data type – fault outcome

Monitor  
Control/Pointer  
Data

- Instrument code
- Fault Injection



# Data Categorization of Fault Outcomes



**High correlation between Control Non-Pointer and EDC/Non-EDC**

## Step 2: Heuristics

```
void conv422to444 (char *src, char *dst, int height, int width, int
offset) {
    for(j=0; j < height; j++){
        for(i=0; i < width; i++) {
            imI = (i < I) ? 0 : i - I
            ...
            dst[imI] = Clip[(2I*src[imI])>>8];
        }
        if( j + I < offset) {
            src += w;
            dst += width; }
    }
}
```

## Step 2: Heuristics

*Faults affecting branches with large amount of data within branch body, has a higher likelihood of resulting in EDC outcomes*

```
void conv422to444 (char *src, char *dst, int height, int width, int
offset) {
    for(j=0; j < height; j++){
        for(i=0; i < width; i++) {
            iml = (i < l) ? 0 : i - l
            ...
            dst[iml] = Clip[(2l*src[iml])>>8];
        }
        if( j + l < offset) {
            src += w;
            dst += width; }
    }
}
```

➤ Fault in  
offset  
➤ Branch Flip

High EDC  
Likelihood

## Step 2: Heuristics

*Faults affecting branches with large amount of data within branch body, has a higher likelihood of resulting in EDC outcomes*

```
void conv422to444 (char *src, char *dst, int height, int width, int
offset) {
    for(j=0; j < height; j++){
        for(i=0; i < width; i++) {
            imI = (i < I) ? 0 : i - I
            ...
            dst[imI] = Clip[(2I*src[imI])>>8];
        }
        if( j + I < offset) {
            src += w;
            dst += width; }
    }
}
```

The diagram shows a flow from a circled assignment statement `dst[imI] = Clip[(2I*src[imI])>>8];` to a box labeled "Low EDC Likelihood". A red circle highlights the assignment statement, and a red arrow points from it to the box. The box is dark blue with white text.

➤ Fault in  
result of  
branch

Low EDC  
Likelihood

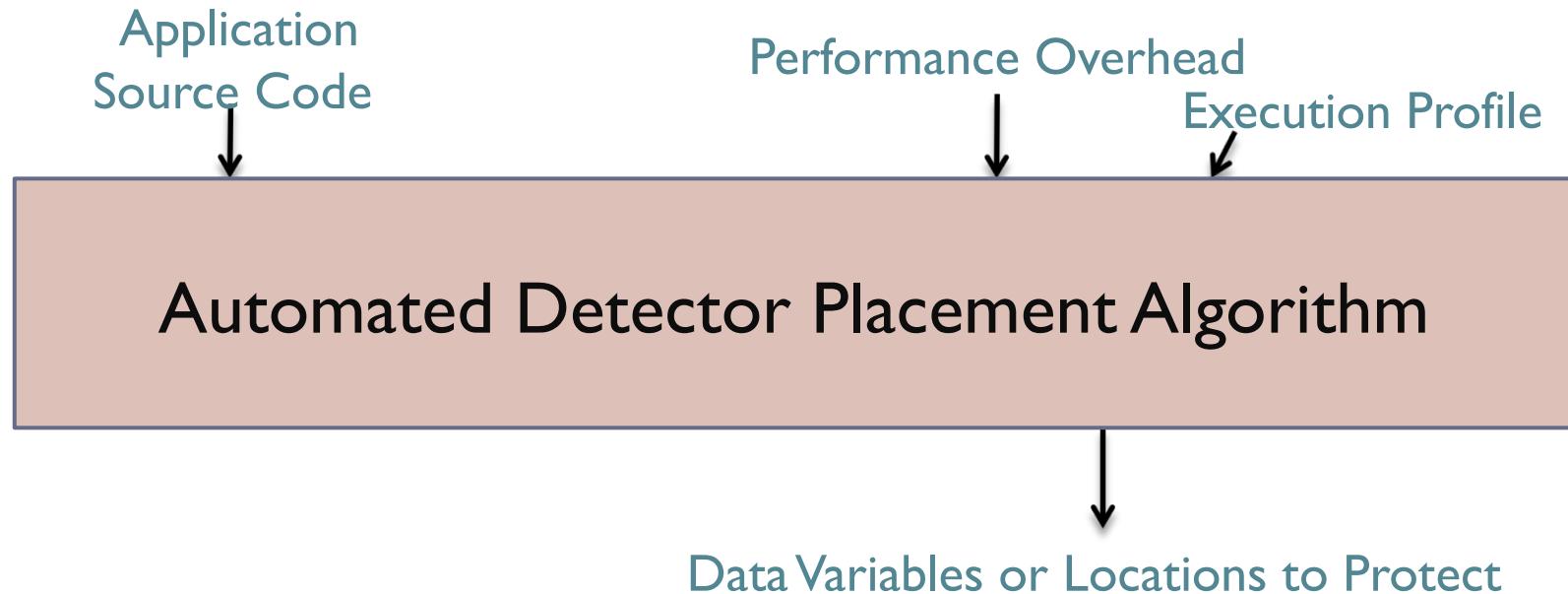
# Heuristics: Main Take Aways

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- Program level, applied to soft computing applications
- Dependent on size of data affected
- Based entirely on static analysis of code

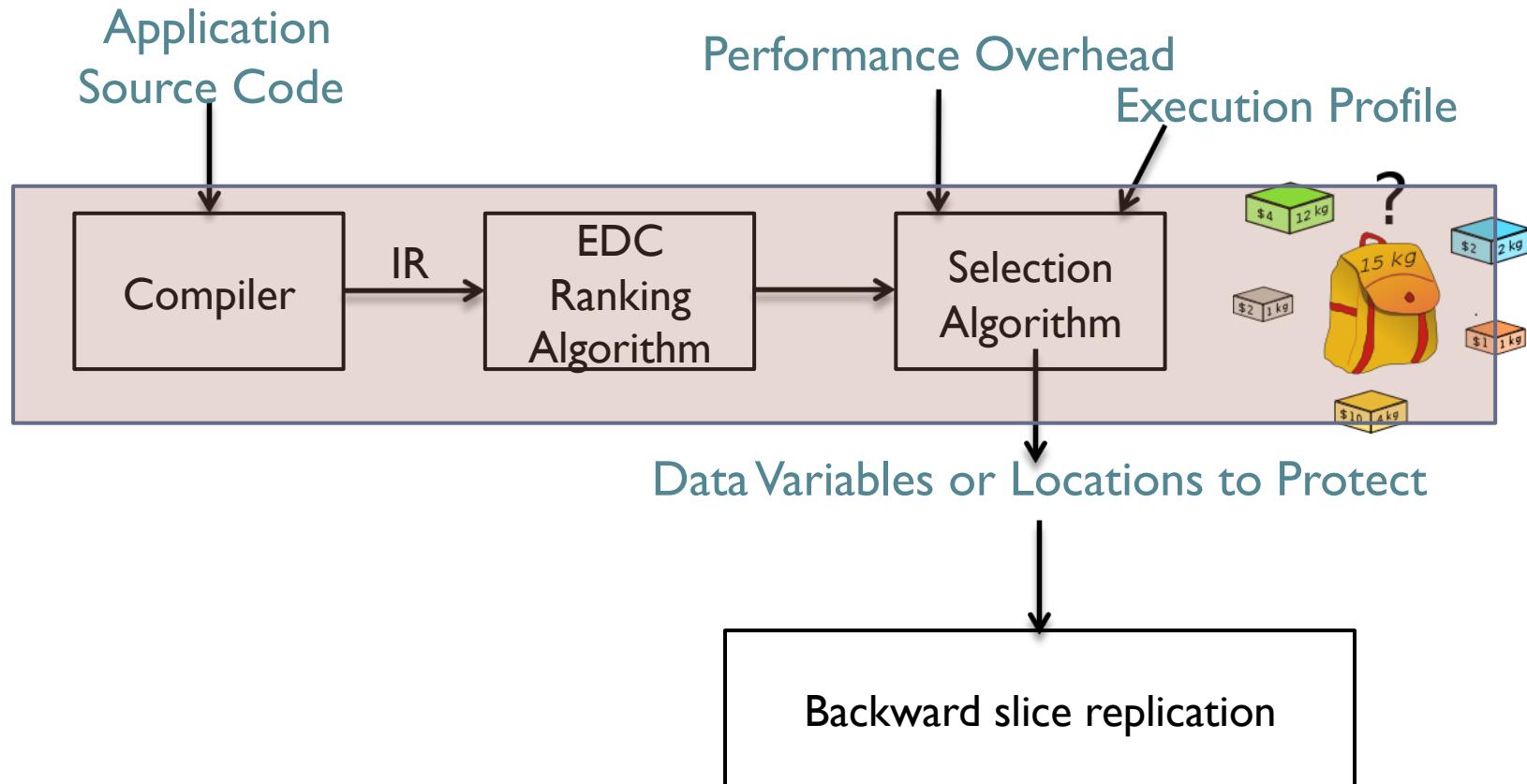
## Step 3: Algorithm

Pre-emptive, Selective detection of EDC causing faults



## Step 3: Algorithm

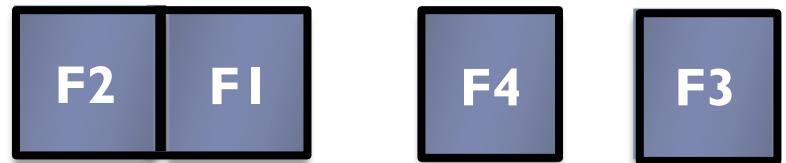
Pre-emptive, Selective detection of EDC causing faults



# Selection Algorithm

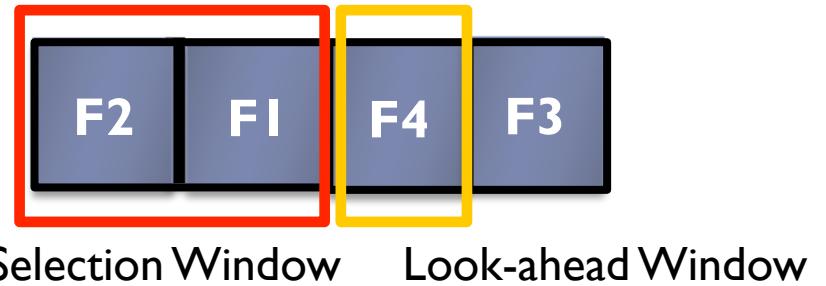
```
void F1(...) {  
    for(i = k; i < num; i++)  
        ...  
}  
  
void F2(void *src, void *dst, ...) {  
    if(src < dst + offset)  
        return;  
    for(j = 0; j < width; j++)  
        ....  
}  
  
void F3(void * src, void *dst,...) {  
    for(i =0; i < n; i++){  
        if( k < r )  
            src += k;  
        ...  
    }  
}  
  
void F4(...){  
    ...  
    k = F5 (...);  
}
```

Function Exec Time  
**F2 > F1> F4 > F3**



# Selection Algorithm

```
void F1(...) {  
    for(i = k; i < num; i++)  
        ...  
}  
void F2(void *src, void *dst, ...) {  
    if(src < dst + offset)  
        return;  
    for(j = 0; j < width; j++)  
        ....  
}  
void F3(void * src, void *dst,...) {  
    for(i =0; i < n; i++){  
        if( k < r )  
            src += k;  
        ...  
    }  
void F4(...){  
    ...  
    k = F5 (...);  
}
```

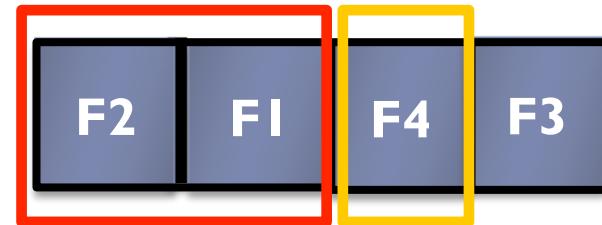


# Selection Algorithm

```

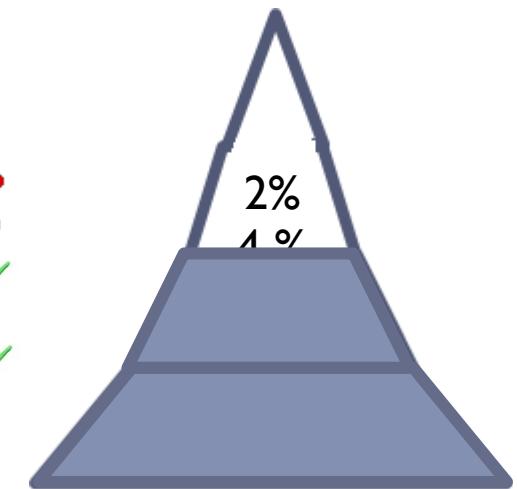
void F1(...) {
    for(i = k; i < num; i++) B1
    ...
}
void F2(void *src, void *dst, ...) {
    if(src < dst + offset) B2 ←
        return;
    for(j = 0; j < width; j++) B3
    ....
}
void F3(void * src, void *dst,...) {
    for(i =0; i < n; i++){
        if( k < r )
            src += k;
        ...
    }
}
void F4(...){
    ...
    k = F5 (...); C1
}

```



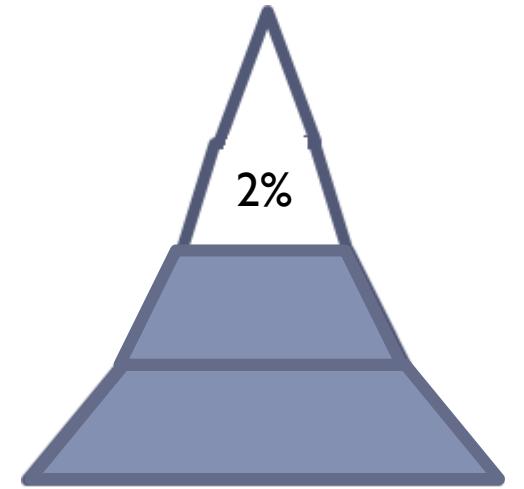
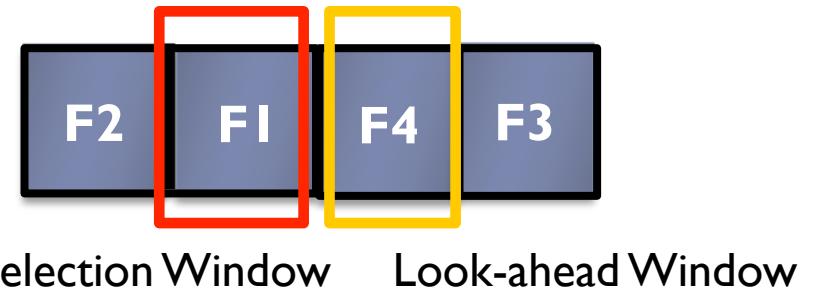
Selection Window      Look-ahead Window

Inst	Rank	P.O. (%)
B2	3	10
B1	2.5	1
B3	2.5	2
C1	0.8	2



# Selection Algorithm

```
void F1(...) {  
    for(i = k; i < num; i++)  
        ...  
}  
  
void F2(void *src, void *dst, ...) {  
    if(src < dst + offset)  
        return;  
    for(j = 0; j < width; j++)  
        ....  
}  
  
void F3(void * src, void *dst,...) {  
    for(i =0; i < n; i++){  
        if( k < r )  
            src += k;  
        ...  
    }  
}  
  
void F4(...){  
    ...  
    k = F5 (...);  
}
```

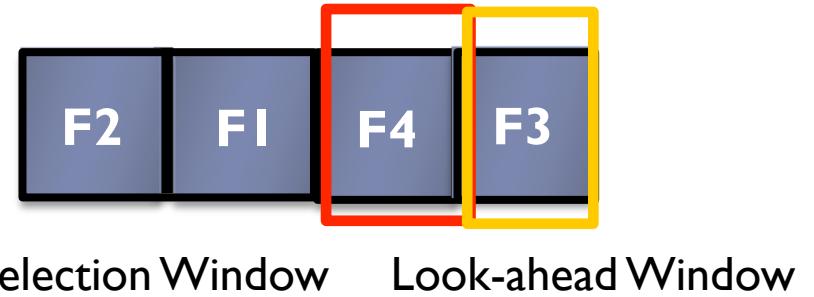


# Selection Algorithm

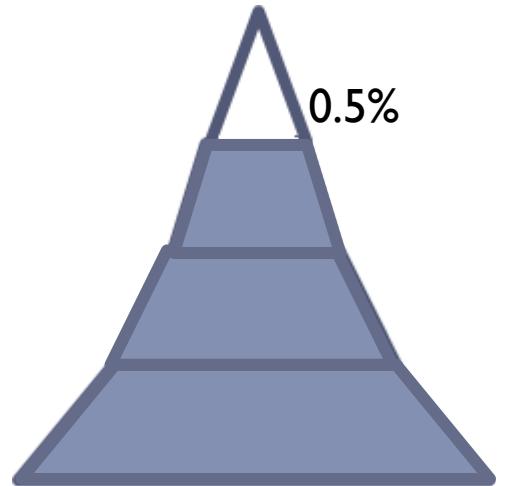
```

void F1(...) {
    for(i = k; i < num; i++)
        ...
}
void F2(void *src, void *dst, ...) {
    if(src < dst + offset)
        return;
    for(j = 0; j < width; j++)
        ....
}
void F3(void * src, void *dst,...) {
    for(i =0; i < n; i++){ B4 ←
        if( k < r )      B5
            src += k;    PI
        ...
    }
    void F4(...){
        ...
        k = F5 (...); CI
    }
}

```



Inst	Rank	P.O. (%)	
B4	3	10	✗
B5	2.5	1.5	✓
PI	1	5	✗
CI	0.8	2	✗

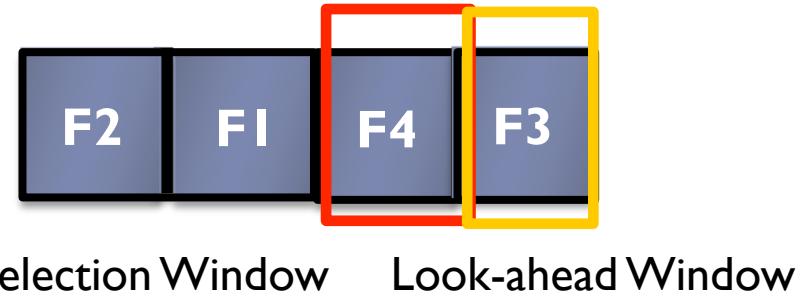


# Selection Algorithm

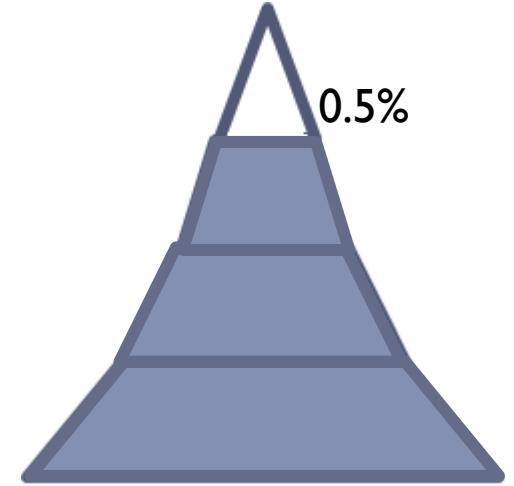
```

void F1(...) {
    for(i = k; i < num; i++) B1
    ...
}
void F2(void *src, void *dst, ...) {
    if(src < dst + offset) B2
    return;
    for(j = 0; j < width; j++) B3
    ....
}
void F3(void * src, void *dst,...) {
    for(i =0; i < n; i++){ B4
        if( k < r ) B5
        src += k;    PI
    }
}
void F4(...){
    ...
    k = F5 (...); C1
}

```



Detector Locations under 5% P.O.  
B1 :  $i < num$   
B3:  $j < width$   
B5:  $k < r$



# Outline

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- ▶ Motivation
- ▶ Approach
- ▶ Experimental Setup and Results

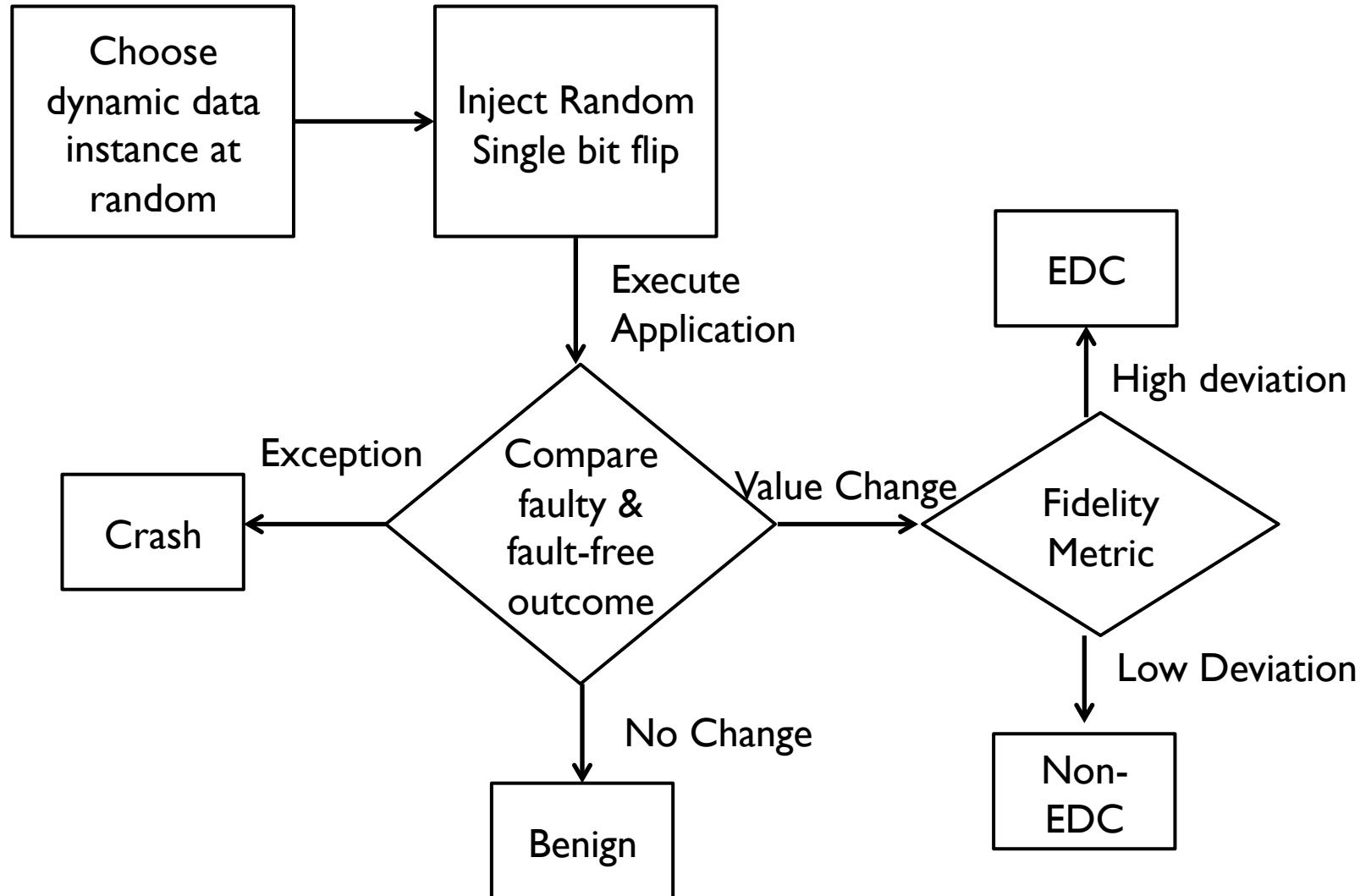
- ▶ Conclusion

# Experimental Setup

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- Six Benchmarks from MediaBench, Parsec Suite
  - Fidelity Metric: PSNR, scaled distortion [Misailovic'12]
- Performed fault injections using LLFI
  - 2000 fault injections, one fault per run (1.3% at 95% CI)
- Measured coverage under varying performance overhead bounds

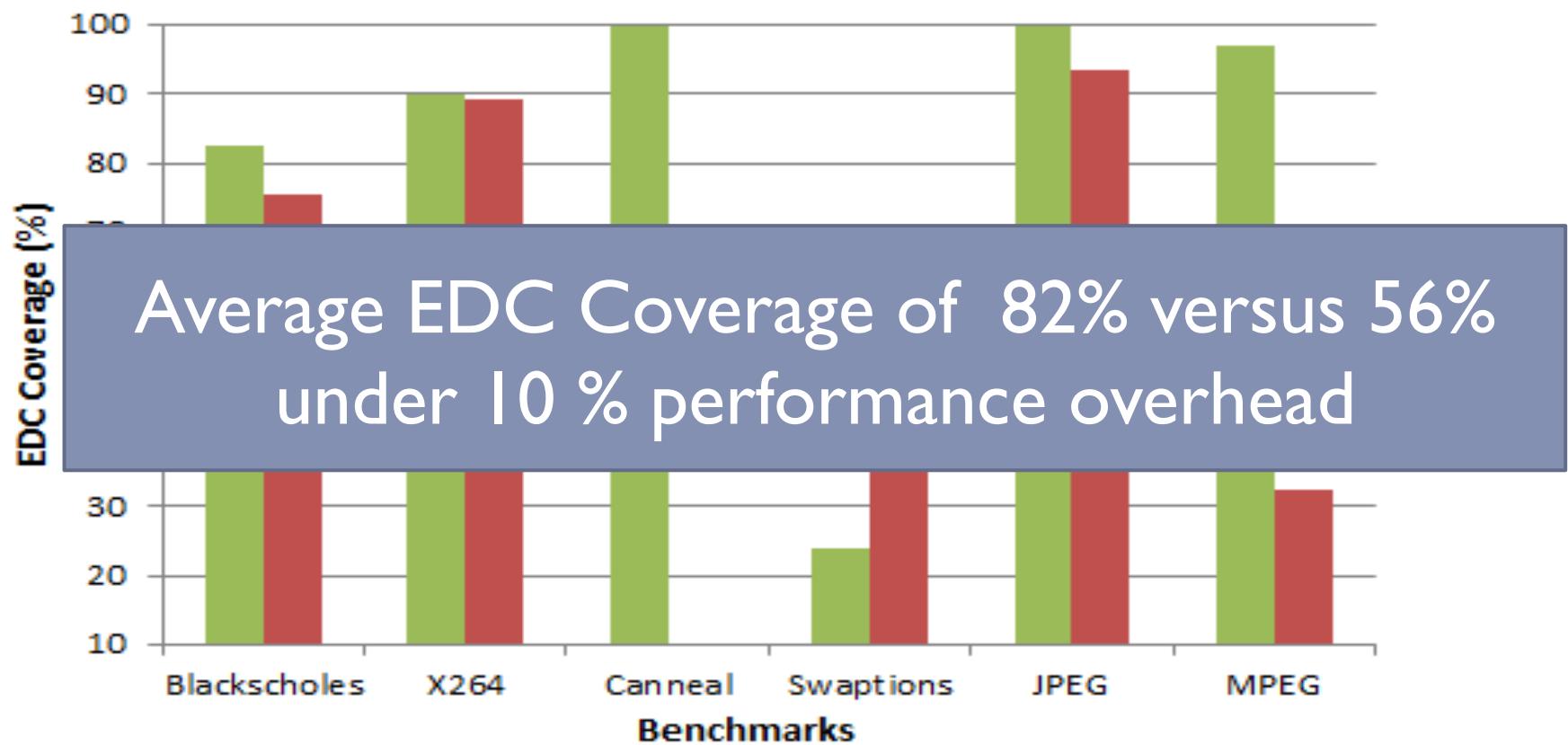
# LLFI Experiment Framework



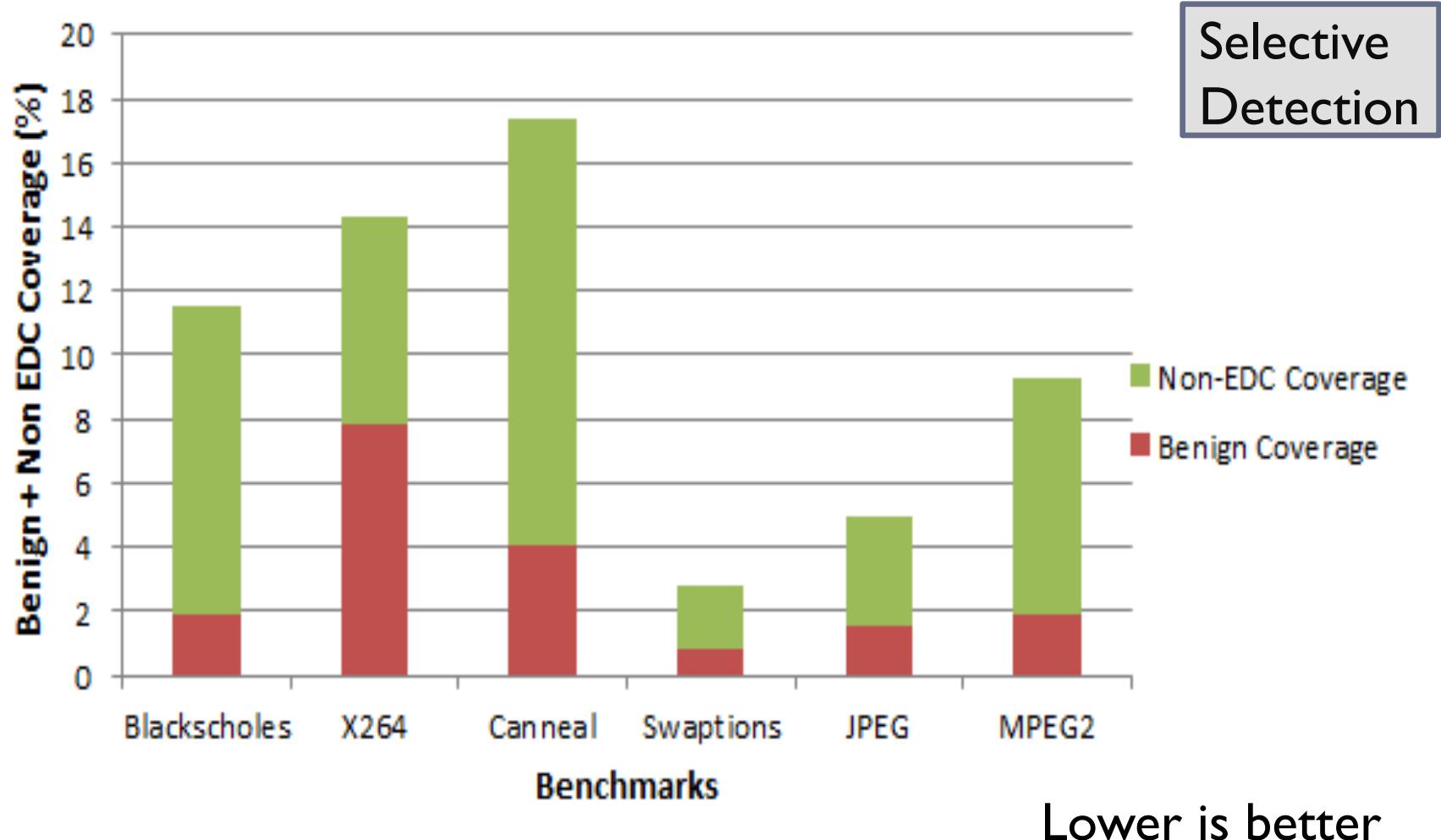
# Coverage Evaluation

$$EDC\ Coverage = \frac{Number\ of\ Detected\ EDCs}{Total\ Number\ of\ EDCs}$$

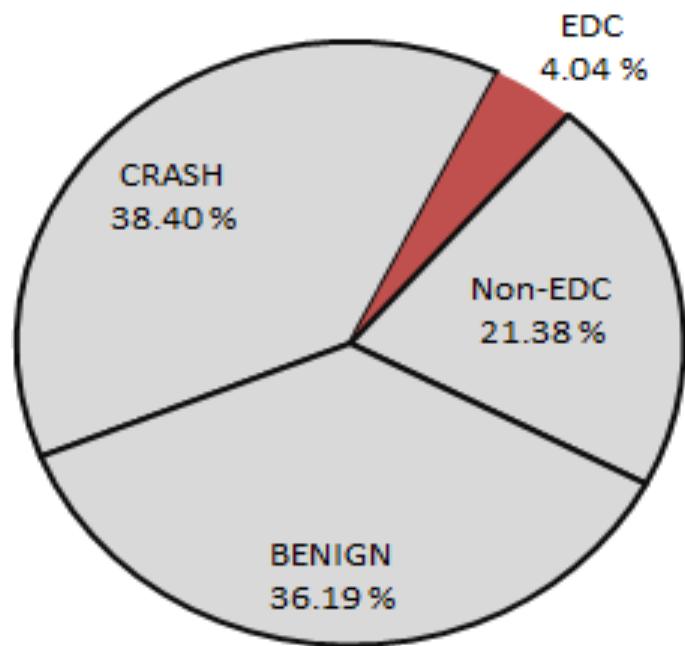
Pre-emptive  
Detection



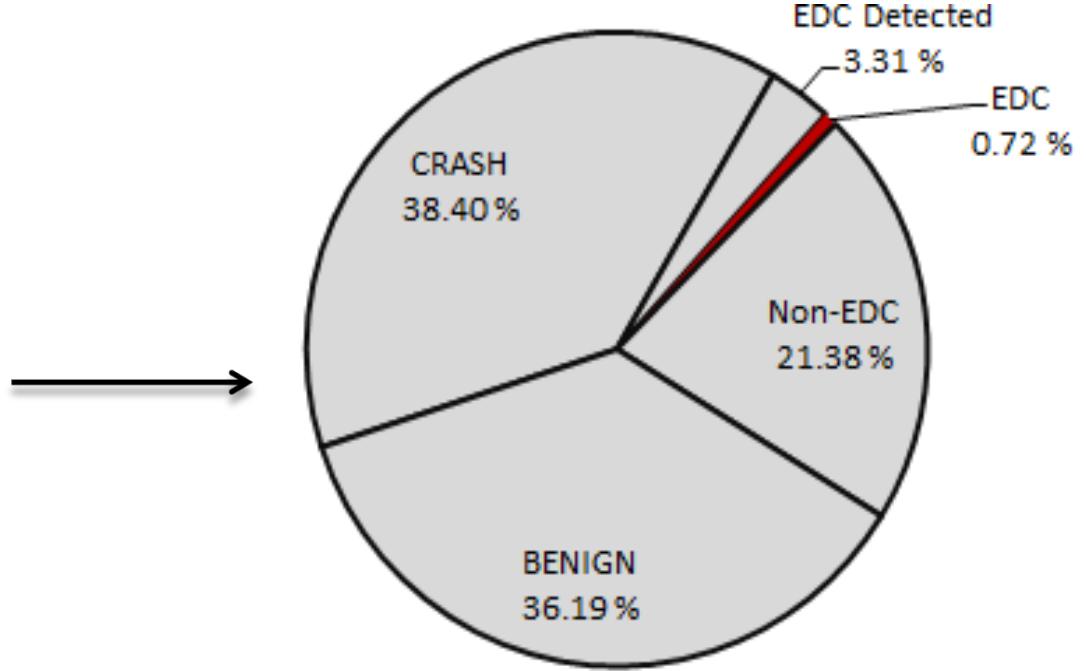
# Coverage Evaluation



# Coverage Numbers in Perspective



Initial Coverage: 95.95 %



Coverage With our Technique: 99.3 %

# Outline

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# Conclusion

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- **Soft Computing applications**
  - Egregious Data Corruptions (EDCs) are unacceptable outcomes
- **Detector Placement Technique: pre-emptive and selective**
  - Program level Heuristics – static analysis of code
  - Automated algorithm - varying performance overhead bounds
- **Future Work**
  - Actual detectors coverage
  - Compiler optimizations effect on technique

LLFI: <http://github.com/DependableSystemsLab/LLFI>

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