Understanding Error Propagation in Deep Learning Neural Network (DNN) Accelerators and Applications

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Motivation

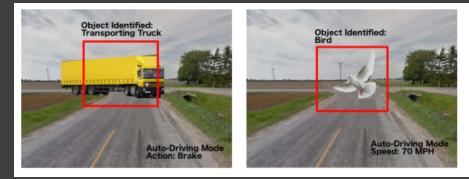
- Neural network applications are widely deployed nowadays
 - Deep learning neural network (DNN): Robots, satellites, cars etc
 - Safety-critical: Detecting cars and pedestrians in self-driving cars
- DNN accelerators are crucial
 - High throughput for real-time inferencing
 - Nvidia NVDLA and Google TPU



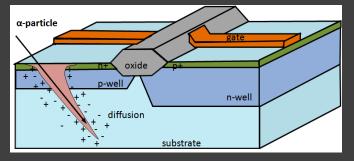


Soft Error

- Transient hardware error
 - Caused by high-energy particles
 - Random single bit-flip
- Silent Data Corruptions (SDCs)
 - Results in wrong prediction of DNN application
- Safety standard requires low SoC FIT for cars
 - ISO26262



Observed SDC



Current Solutions

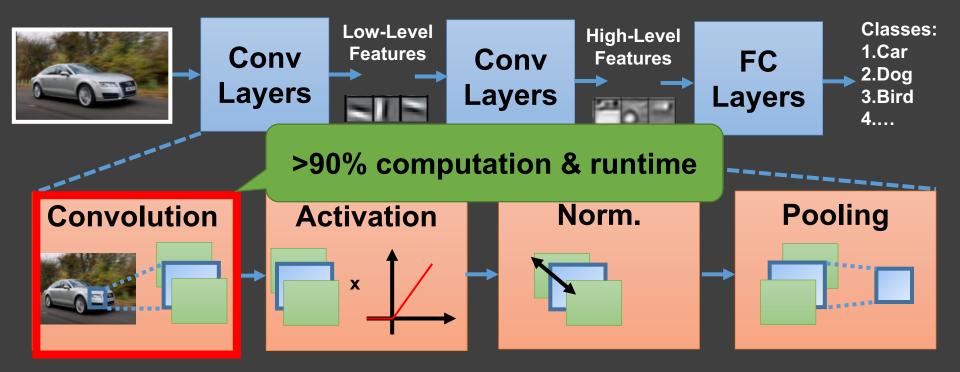
- Traditionally
 - Triple Modular Redundancy (TMR) for execution units
 - Error Correction Code (ECC) for DRAMs
- Other protection techniques
 - DNN-algorithm agnostic
 - Generic micro-arch

Non-optimal for DNN applications & accelerators

Goal

- Understand error propagation in DNN applications & accelerators
 - Quantification
 - Characterization
- Based on the insights, mitigate SDC:
 - Efficient way to detect errors

DNN Explained



DNN Accelerator & Fault Model

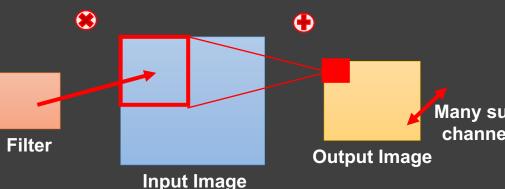
Fault Model:

- Latch Faults
- Buffer Faults

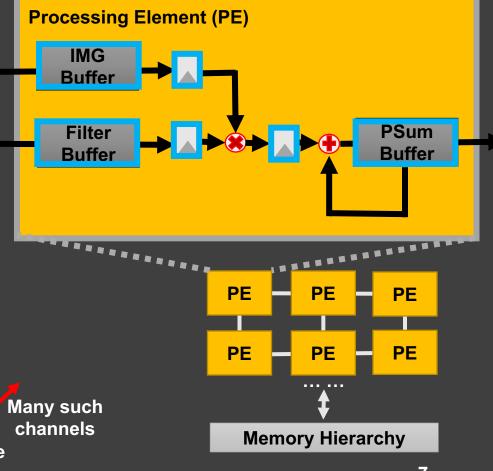
Convolution Dot

Product

Partial Sum Accum.



Spatial Architecture



Experimental Setup

- Fault Injection
 - Map arch. component to C code in Tiny-CNN
 - 3,000 random faults per component per layer (error bar: 0.11%~0.34%)
 - 1 fault injected per run
 - Popular pre-trained DNNs with ImageNet / CIFAR-10

```
// Simulation in Tiny-CNN
function feed_forward(){
    ...
    weight = inject_fault (weight);
    multiply = weight * img;
    ...
}
```

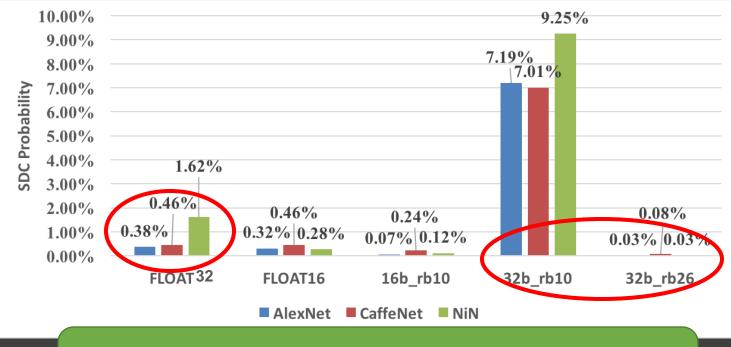
Experiment Setup

- Silent Data Corruption (SDC)
 - Mismatch between winner of fault-free execution
- Generic DNN Accelerator & Eyeriss
 - FP: Float32 and Float16 floating point



- RQ1: What are SDCs in different DNNs using different data types ?
- RQ2: Which bits are sensitive to SDCs in different data types ?
- RQ3: How do errors affect values that result in SDCs?
- RQ4: How does error propagate layer by layer ?
- RQ5: What is the SDC sensitivity in different data reuse buffers?

SDC in DNNs



1.SDC probabilities are different in different DNNs

2.SDC probabilities vary a lot using different data types

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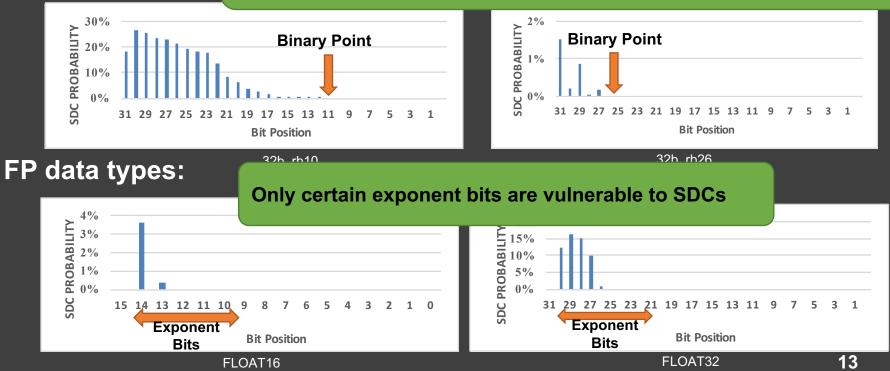
Bit Positions

FxP data types:

Error Mitigation:

- Restrain dynamic value range in data type
- Selective latch hardening
- 1. High-order bits are vulnerable
- 2. Larger dynamic value range leads to higher SDC probability

3. Sliding binary point controls the amount of vulnerable bits

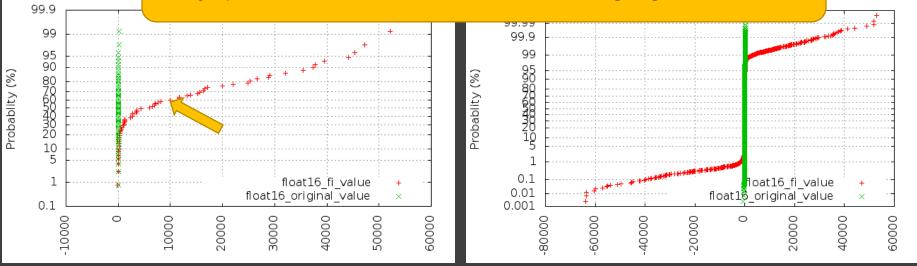


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Value Changes under Errors



Symptom-based error detector: Check value range against errors



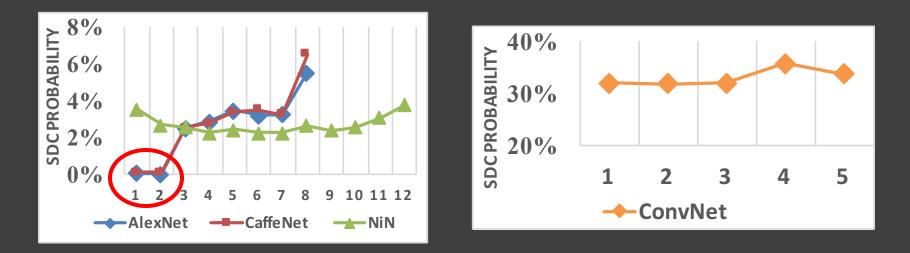
SDC

Benign

If the numeric value is modified to be a large positive one by faults, it likely causes SDC

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SDC in Different Layers



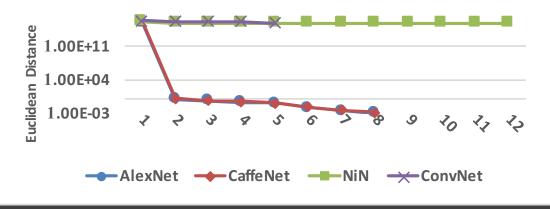
1.SDC probability increases by layers

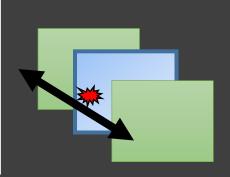
2.Layer 1&2 have lower SDC probabilities in AlexNet and CaffeNet

Normalization Layer

Error Mitigation

Error detectors can be placed after LRN





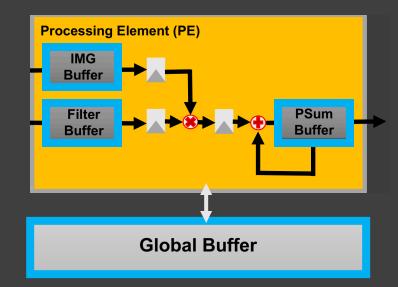
* Faults injected at first layer only

- 1. Euclidean distance decreases by layers in AlexNet and CaffeNet
- 2. Local Response Normalization (LRN) in AlexNet & CaffeNet in Layer 1&2 re-normalizes values back towards normal range

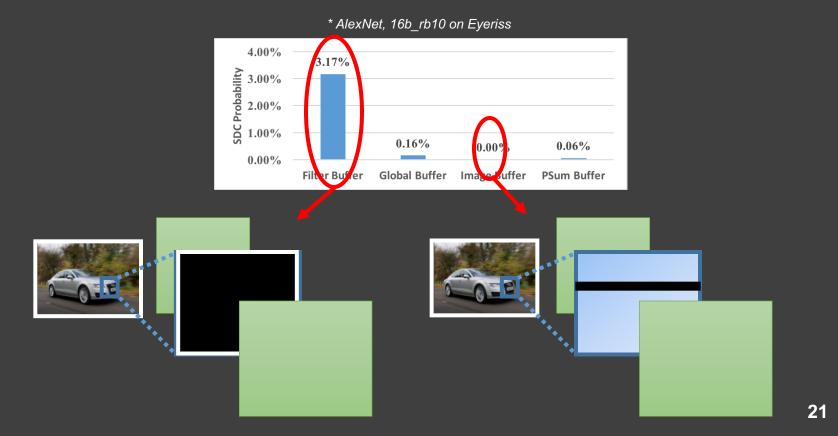
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Buffer Faults

- Eyeriss: Row-Stationary Dataflow
 - Global Buffer: Reuse image data
 - IMG Buffer: Reuse image data of a row
 - Filter Buffer: Reuse filter weights
 - PSum: Reuse partial sum results



Buffer Faults



Summary

- Characterized error propagation which depends on data types, layers, values topologies etc
- Mitigation techniques including value range checker and selective latch hardening

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