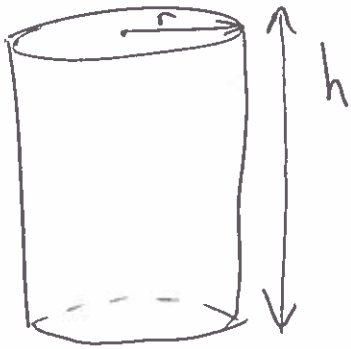


Example (chapter 14.4 n°34 Apex) Lecture 14 (9)

Estimate the amount of metal in a closed cylindrical can, 10cm high, 4cm in diameter, if top and bottom are 0,1cm thick and sides 0,05cm thick.




$$\text{Volume } V = \pi r^2 h$$

$$dV = \frac{\partial V}{\partial r} dr + \frac{\partial V}{\partial h} dh$$

$$dV = \underbrace{2r\pi h}_{\text{surface area of the sides}} dr + \underbrace{\pi r^2}_{\text{surface area of top (or bottom)}} dh$$

$$dV = 2(2)\pi(10)(0,05) + \pi(2)^2(0,1+0,1)$$

$$dV = \frac{40\pi}{20} + 4\pi(0,2) = 2\pi + 0,8\pi = 2,8\pi \approx 8,8 \text{ cm}^3$$

Material for midterm 1 ends here 

Exact calculation for can example: (2)

$$V(r+dr, h+dh) - V(r, h) = \pi(r+dr)^2(h+dh) - \pi r^2 h$$
$$= \pi \left\{ (r^2 + 2rdr + dr^2)(h+dh) - r^2 h \right\}$$

$$= \pi \left\{ r^2 h + r^2(dh) + 2rh(dr) + 2r(dr)(dh) + (dr)^2(dh) + h(dr)^2 - r^2 h \right\}$$

$$= \underbrace{\pi r^2(dh) + 2\pi r h(dr)}_{\substack{\text{Linear terms} \\ \parallel \\ dV}} + \underbrace{2r(dr)(dh) + h(dr)^2}_{\substack{\text{2nd order} \\ \text{Quadratic terms}}} + \underbrace{(dr)^2(dh)}_{\substack{\text{3rd order} \\ \text{terms.}}}$$

These are the error in the linear approximation (as they are missing). Higher order terms in  $dr, dh$ . Corrects for what is missing in linear approximation

Chain rule  $y = f(g(t)) \quad \frac{dy}{dt} = f'(g(t)) g'(t) \quad (3)$

here  $y = f(x)$  with  $x = g(t)$

$\frac{dy}{dt} = \frac{dy}{dx} \frac{dx}{dt} \Rightarrow$  This is the single variable chain rule.

$\Rightarrow$  more variables:

$z = f(g(t), h(t))$  again  $z = f(x, y)$  with  $x = g(t)$  and  $y = h(t)$ .

$\frac{dz}{dt} = \frac{\partial z}{\partial x} \frac{dx}{dt} + \frac{\partial z}{\partial y} \frac{dy}{dt}$

recall differential  
 $dz = \frac{\partial z}{\partial x} dx + \frac{\partial z}{\partial y} dy$

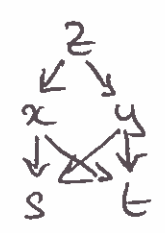
if  $z = f(x, y)$  with  $x = g(s, t)$  and  $y = h(s, t)$

then  $\frac{\partial z}{\partial s}$  and  $\frac{\partial z}{\partial t}$  are given by

$\frac{\partial z}{\partial s} = \frac{\partial z}{\partial x} \frac{\partial x}{\partial s} + \frac{\partial z}{\partial y} \frac{\partial y}{\partial s}$   
 $\frac{\partial z}{\partial t} = \frac{\partial z}{\partial x} \frac{\partial x}{\partial t} + \frac{\partial z}{\partial y} \frac{\partial y}{\partial t}$

The derivatives with respect to  $s$  are now partial because we "fixed"  $t$ .

dependency graph



example: switching to polar coordinates.

④

$$z = f(x, y) \quad x = r \cos \theta \quad y = r \sin \theta$$

$$\frac{\partial z}{\partial r} = \frac{\partial z}{\partial x} \frac{\partial x}{\partial r} + \frac{\partial z}{\partial y} \frac{\partial y}{\partial r}$$

$$\frac{\partial z}{\partial r} = \cos \theta$$

$$\frac{\partial z}{\partial \theta} = \frac{\partial z}{\partial x} \frac{\partial x}{\partial \theta} + \frac{\partial z}{\partial y} \frac{\partial y}{\partial \theta}$$

$$\frac{\partial z}{\partial \theta} = \sin \theta$$

$$\frac{\partial z}{\partial r} = \frac{\partial z}{\partial x} \cos \theta + \frac{\partial z}{\partial y} \sin \theta$$

$$\frac{\partial x}{\partial \theta} = -r \sin \theta$$

$$\frac{\partial y}{\partial \theta} = r \cos \theta$$

$$\frac{\partial z}{\partial \theta} = -\frac{\partial z}{\partial x} r \sin \theta + \frac{\partial z}{\partial y} r \cos \theta$$

problem: compute  $\left(\frac{\partial z}{\partial r}\right)^2 + \frac{1}{r^2} \left(\frac{\partial z}{\partial \theta}\right)^2$  in terms of  $\frac{\partial z}{\partial x}$ ,  $\frac{\partial z}{\partial y}$

$$\Rightarrow \left(\frac{\partial z}{\partial x} \cos \theta + \frac{\partial z}{\partial y} \sin \theta\right)^2 + \frac{1}{r^2} \left(-\frac{\partial z}{\partial x} r \sin \theta + \frac{\partial z}{\partial y} r \cos \theta\right)^2$$

$$= \left(\frac{\partial z}{\partial x}\right)^2 (\cos^2 \theta + \sin^2 \theta) + \left(\frac{\partial z}{\partial y}\right)^2 (\sin^2 \theta + \cos^2 \theta)$$

$$+ 2 \frac{\partial z}{\partial x} \frac{\partial z}{\partial y} \cos \theta \sin \theta - \frac{2}{r^2} r \sin \theta r \cos \theta \frac{\partial z}{\partial x} \frac{\partial z}{\partial y}$$

$$\Rightarrow \left(\frac{\partial z}{\partial r}\right)^2 + \frac{1}{r^2} \left(\frac{\partial z}{\partial \theta}\right)^2 = \left(\frac{\partial z}{\partial x}\right)^2 + \left(\frac{\partial z}{\partial y}\right)^2$$

## Chain rule and implicit differentiation

We can use the chain rule to better understand implicit differentiation. Suppose we have an equation  $F(x, y, z) = 0$ , if we can explicitly solve this equation for  $z$ , we get  $z = f(x, y)$ , some function of  $(x, y)$ .

Maybe we can't solve it explicitly but we can regard  $F(x, y, z) = 0$  as  $z = f(x, y)$  such that  $F(x, y, f(x, y)) = 0$ .

example  $2x + 3y - 4z - e^{xyz-1} = 0$

$\Rightarrow$  can't solve for  $z$ . We can get  $\frac{\partial z}{\partial x} = f_x$  and  $f_y = \frac{\partial z}{\partial y}$  by differentiations  $F(x, y, z) = 0$  with respect to  $x$  or  $y$ .