CORGIDS: A Correlation-based Generic Intrusion Detection System

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Introduction

- Cyber-Physical system (CPS) consist of software and physical components knitted together.
- Properties in CPS must follow laws of physics.
- **Physical properties** of a drone: altitude, distance travelled, speed, and flight time.







Security attacks in CPS

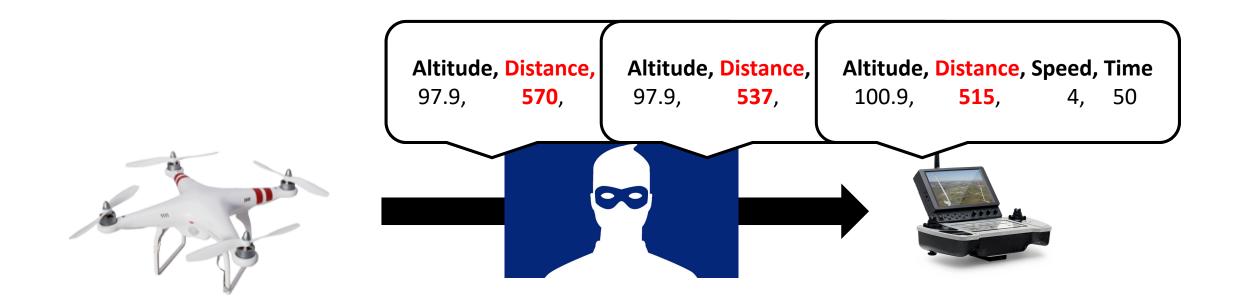
- The Jeep Hack (http://illmatics.com/carhacking.html)
- Hackable Cardiac Devices from St. Jude (https://medsec.com/stj_expert_witness_report.pdf)
- TRENDnet Webcam Hack (https://www.wired.com/2012/02/home-cameras-exposed/)







Distance Spoofing Attack



What is an Invariant?

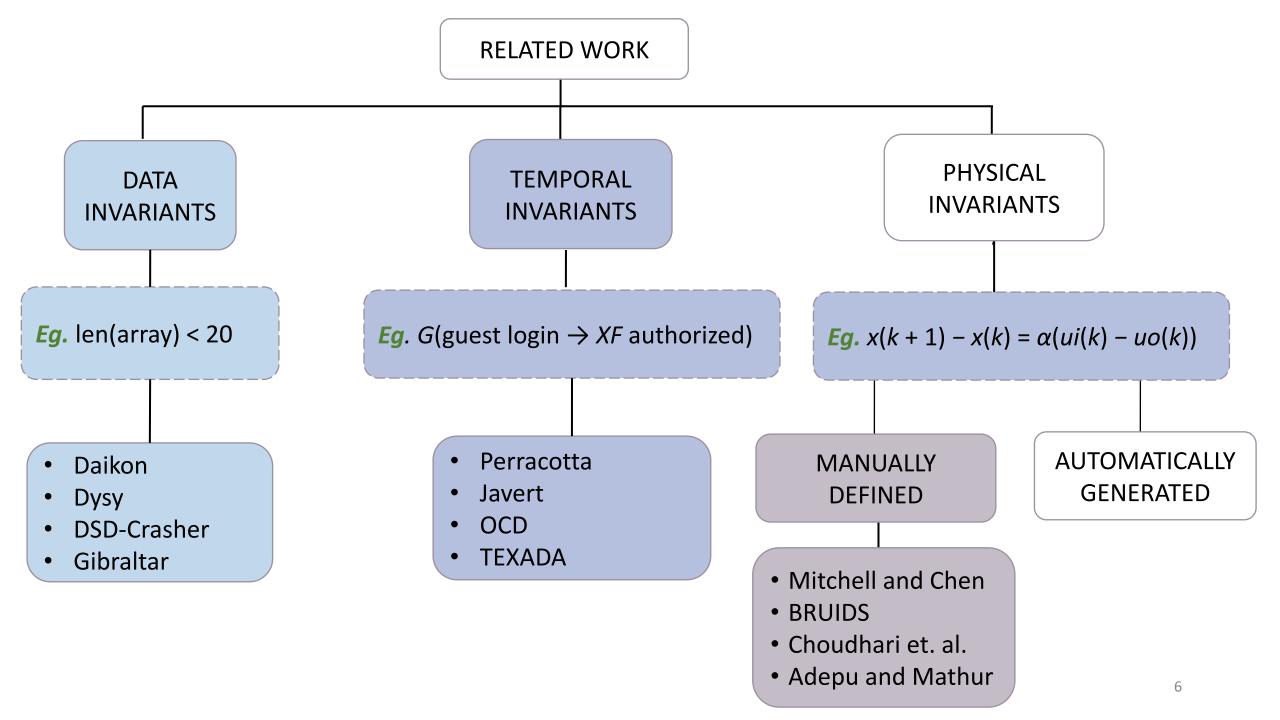
"Something that does not change under a transformation"



Take away:

- **Invariants** are used to **detect** security attacks.
- CORGIDS uses physical invariants to detect intrusion

Speed $\propto \frac{1}{Time}$



Automatically Generated Physical Invariants



Physical invariants

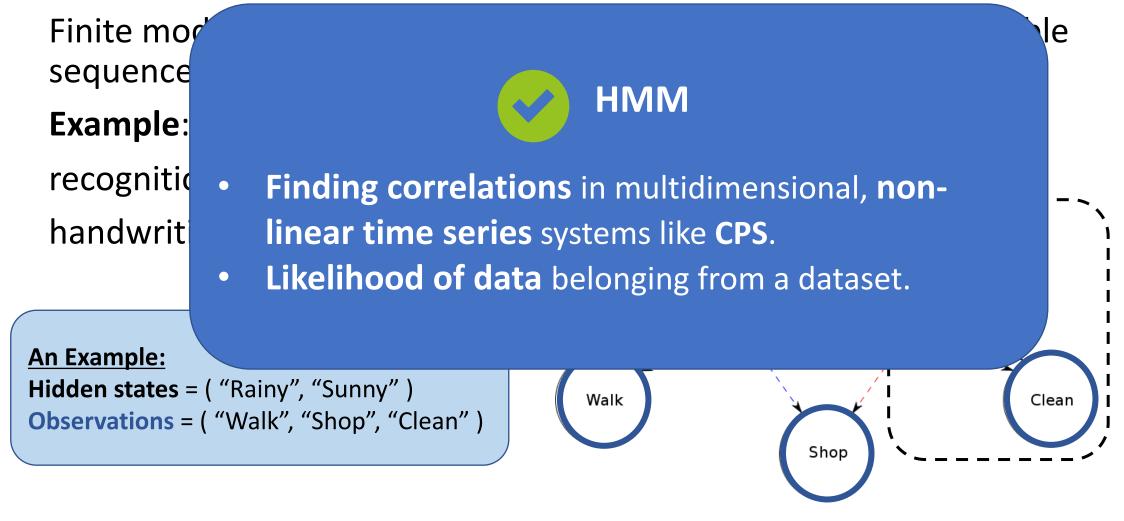
Contributions

- Use Hidden Markov Models (HMM) to infer the logical correlations to detect intrusions.
- Design CORrelation based Generic Intrusion Detection System CORGIDS.
- Demonstrate CORGIDS on two CPS an unmanned aerial vehicle (UAV) and a smart artificial pancreas (SAP).
- Perform five targeted attacks on the CPS.
- CORGIDS is able to successfully detect attacks.

Threat Model

- Capability to gain read and write access to the communication channel between the system under test (SUT) and controller.
- Has root access to the SUT.
- Capable of spoofing, flooding, tampering, and rebooting.

Hidden Markov Model (HMM)

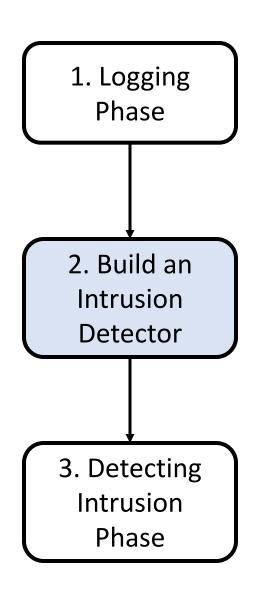


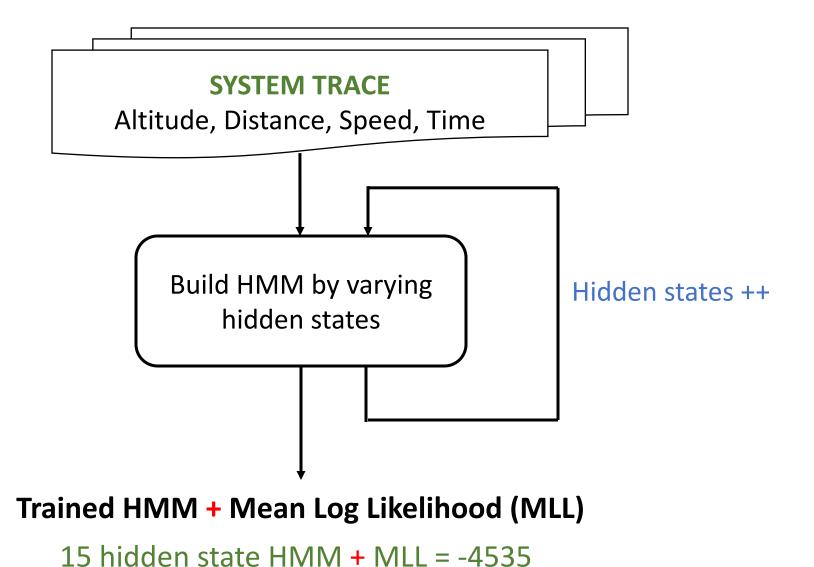
Work-flow of CORGIDS

1. Logging Phase 2. Build an Intrusion Detector 3. Detecting Intrusion Phase

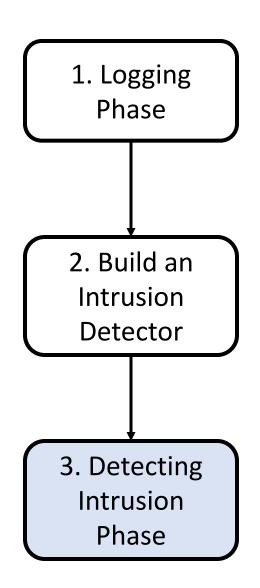
Altitude (m)	Battery left (%)	Distance travelled (m)	Flight time (s)
40	89	42.1445	38.32
40	89	44.2563	39.342
40	89	47.2397	40.356
40	89	51.0202	41.376
40	88	55.2434	42.345
40	88	59.5897	43.346
40	88	64.1632	44.335
41	88	68.8979	45.323
41	88	73.7389	46.351
41	87	78.6564	47.448
41	87	83.6196	48.551

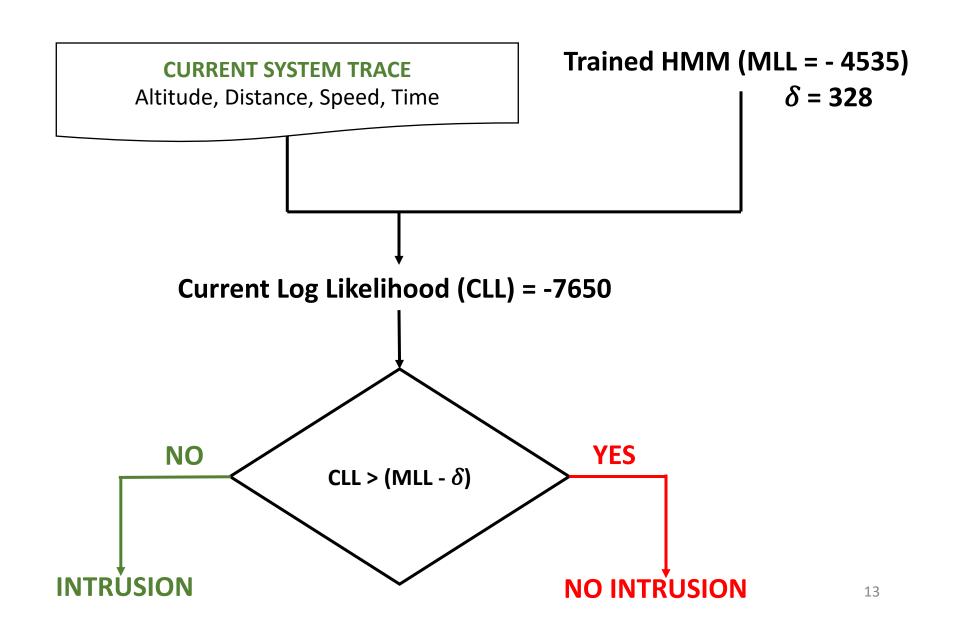
Work-flow of CORGIDS





Work-flow of CORGIDS





Experimental setup

Unmanned Aerial Vehicle (UAV)

ArudPilot's Software in the Loop (SITL)

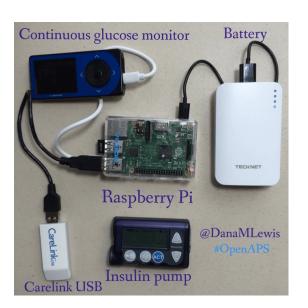
(http://ardupilot.org/dev/docs/sitl-simulator-software-in-the-loop.html)

Smart Artificial Pancreas (SAP)

Open Artificial Pancreas System (OpenAPS)

(https://openaps.org/)





Attacks

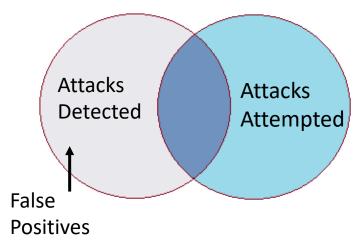
- UAV
 - Distance Spoofing
 - Flooding
 - Battery Tampering
- SAP
 - Insulin Tampering
 - Glucose Spoofing

Distance Spoofing Attack



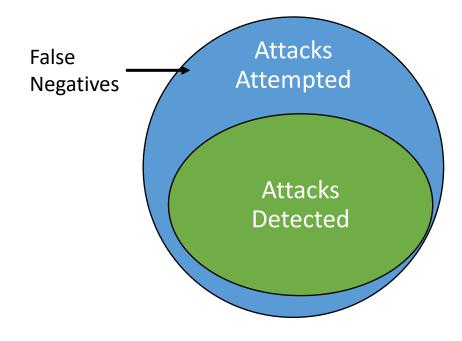
Evaluation Criteria

False positive rate (FP)



- Precision = $\frac{TP}{TP+FP}$
- Recall = 1 FN
- Performance overhead = Additional time take by CORGIDS
- Memory overhead = Additional memory take by CORGIDS

False negative rate (FN)

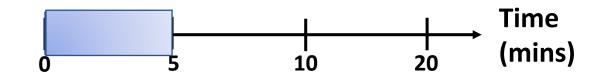


Sensitivity Analysis

Find values of w, δ and λ for which highest value of **Precision** and **Recal**l is achieved.

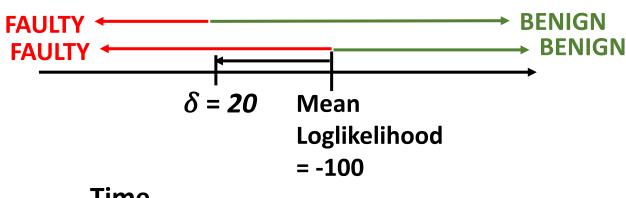
Three experimental factors:

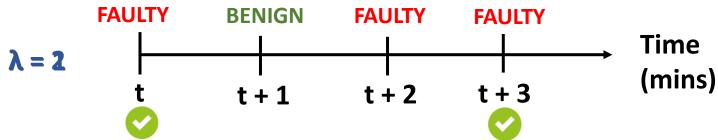
• Window size (w) in minutes



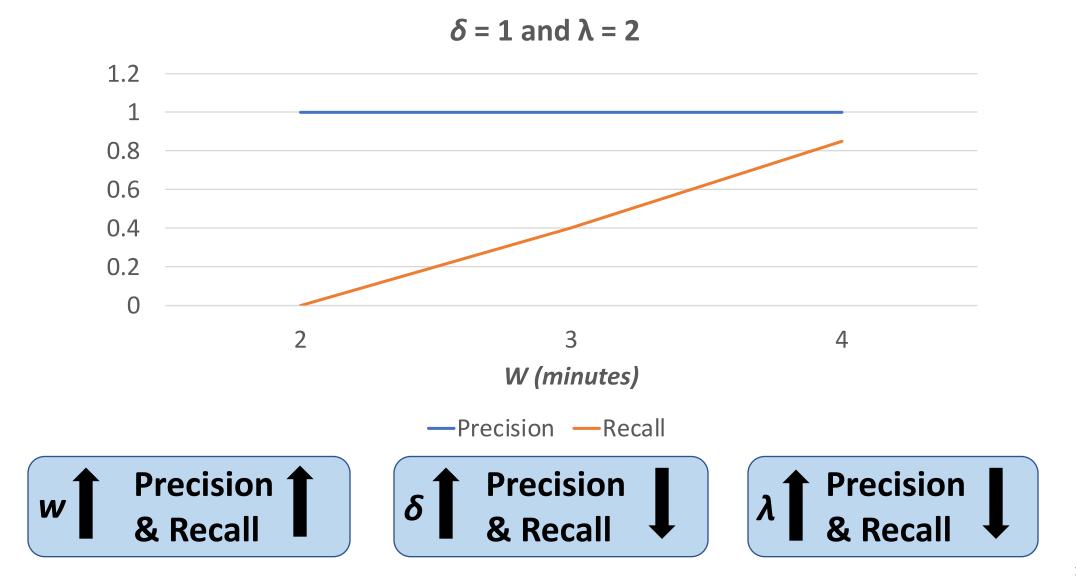
• Acceptable range (δ) in standard deviations

• Threshold of consecutive decisions (λ)





Sensitivity Analysis: Result



Evaluation

TESTBED	TARGETED ATTACKS	FP (%)	FN (%)
UAV	Battery Tampering	0.0	12.20
	Flooding	0.0	11.30
	Distance Spoofing	0.0	12.80
SAP	Insulin Tampering	5.60	4.20
	Glucose Spoofing	2.80	8.40

Table: FP and FN obtained by CORGIDS

Overheads

OpenAPS platform: Raspberry Pi3

Approximately 1GB of RAM
With quad-core 64-bit ARM Cortex running at 1.2 GHz
Average of 10 executions



- Memory overhead
 CORGIDS consumed 36.15 MB
- Memory overhead comparable with other IDS.
- CORGIDS is initial implementation and overhead can be reduced by optimization.

Performance overhead
 CORGIDS took 1.25 seconds

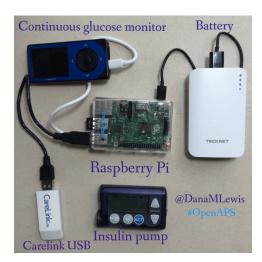
- Execution cycle time 5 minutes
- Time taken by CORGIDS was negligible.



Summary

- Physical properties of CPS are indicative of its behavior.
- HMM are good at finding correlations among properties.
- CORGIDS was able to detect intrusion with higher Precision and Recall.





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