

Reminder :

- Webwork 1 is due on Friday, Sept 14.

- Office hours :

Thurs 4-5 pm

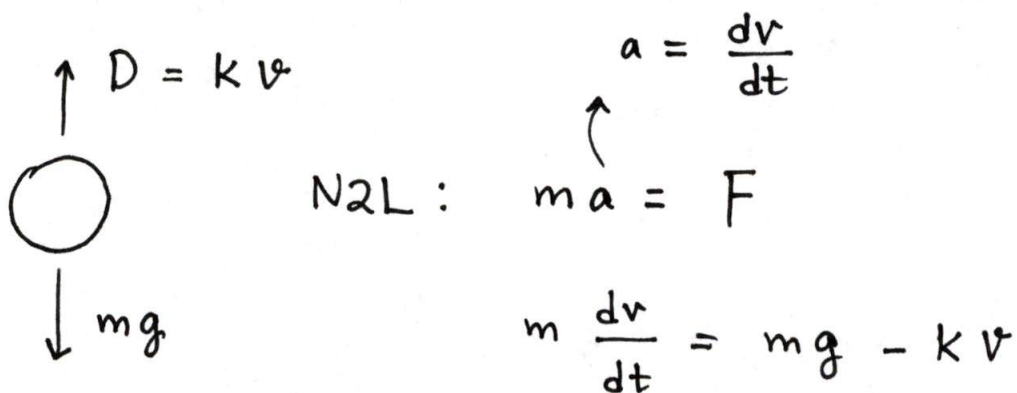
Fri 4-5:30 pm

New
location →

Location: MATH ANNEX
Room 1118

Last Class :

Falling Object Model :



1st order
linear ODE ←

$$\boxed{\frac{dv}{dt} = g - \frac{k}{m}v} \quad (I)$$

Use integrating factor method to solve (I)

Rewrite as

$$\frac{dv}{dt} + \overset{p(t)}{\left(\frac{k}{m}\right)} v = \overset{g(t)}{g}$$

integrating factor

↑

$$r(t) = e^{\int p(t) dt} = e^{\int \frac{k}{m} dt} = e^{\frac{k}{m} t}$$

$$\frac{d}{dt} \left(e^{\frac{k}{m} t} v \right) = e^{\frac{k}{m} t} g$$

integrate
and simplify

$$v(t) = \frac{mg}{k} + C e^{-\frac{k}{m} t}$$

→ general
solution

* This is also a separable equation, rewrite (I) as

$$\frac{dv}{g - \frac{k}{m} v} = dt \quad \text{and integrate.}$$

$$\int \frac{dv}{g - \frac{k}{m} v} = t + C \Rightarrow -\frac{m}{k} \ln \left(g - \frac{k}{m} v \right) = t + C_1$$

$$C_2 = e^{-\frac{kC_1}{m}}$$

$$\Rightarrow g - \frac{k}{m} v = C_2 e^{-\frac{k}{m} t}$$

$$C_3 = -\frac{m}{k} C_2$$

$$\Rightarrow v = \frac{mg}{k} + C_3 e^{-\frac{k}{m} t}$$

Let's focus on the ODE itself and not on the solution.

$$\frac{dv}{dt} = g - \frac{k}{m} v \quad (\text{I})$$

For simplicity, assume $m = 10 \text{ kg}$

$$k = 2$$

$$g = 9.8 \text{ m/s}^2$$

$$\frac{dv}{dt} = 9.8 - \frac{v}{5} \quad \leadsto \quad \text{solution: } V(t)$$

$\frac{dv}{dt} = v' =$ slope of
the tangent line
to $v(t)$.

Let's pick some values for v ,

and evaluate RHS:

$$v = 40 \quad \leadsto \quad 9.8 - \frac{40}{5} = 9.8 - 8 = \underbrace{1.8}_{\frac{dv}{dt}} \quad \leadsto \text{slope of tangent line:}$$

$$v = 45 \quad \leadsto \quad \text{RHS} = 9.8 - 9 = 0.8 = \frac{dv}{dt}$$

$$v = 50 \quad \leadsto \quad \text{RHS} = 9.8 - 10 = -0.2 = \frac{dv}{dt}$$

$$v = 55 \quad \leadsto \quad \text{RHS} = 9.8 - 11 = -1.2 = \frac{dv}{dt}$$

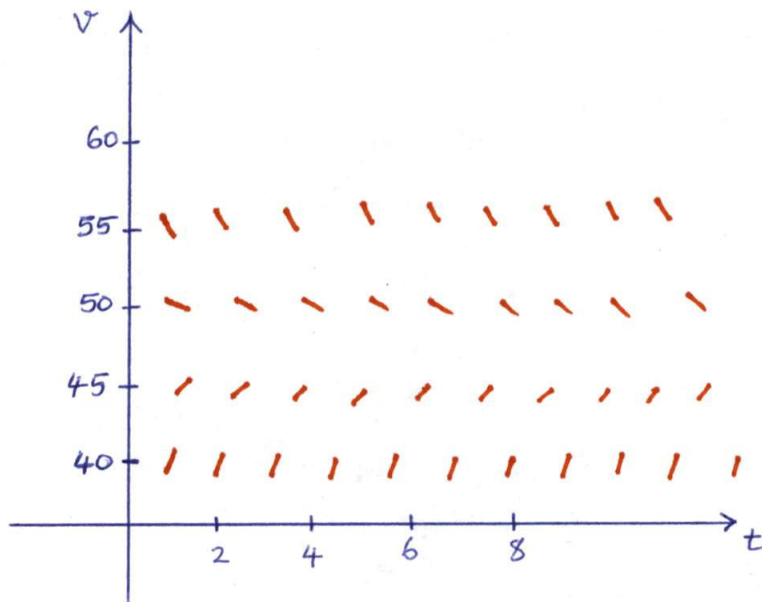
Corresponding to each v , we sketch a line with slope = 1.8, 0.8, ...
for all t .

* If we keep evaluating RHS and sketch the line segments corresponding to slopes we will get

a Slope field or direction field

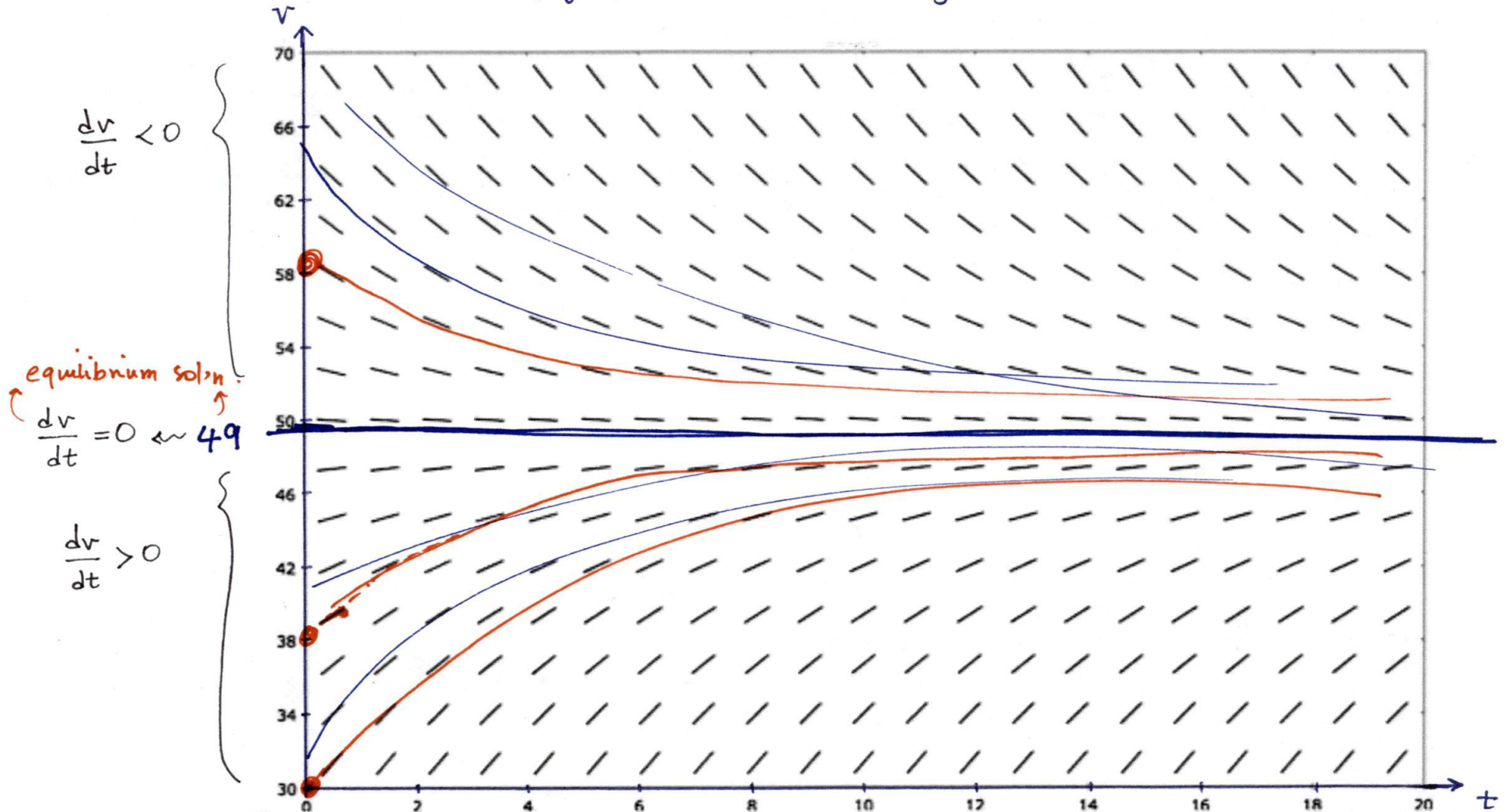
* MATLAB does this for us. Don't Worry 😊

(In a given interval for v and t , we make a grid fine enough so that it can represent the behaviour of the solution.)



Falling Object Model (slope field)

$$\frac{dv}{dt} = g - \frac{k}{m} v \quad \xrightarrow[m=10 \text{ kg}]{k=2, g=9.8} \quad \frac{dv}{dt} = 9.8 - \frac{v}{5}$$



This figure is a slope field or direction field.

Observations :

- ① Following the line segments starting from some initial value $V(0) = V_0$, we'll have a curve for the solution. (different initial value, different curve.)
- ② if v is below a certain critical value then $\frac{dv}{dt} > 0 \rightarrow$ speed of the object is increasing as it falls.

if v is above the certain critical value then $\frac{dv}{dt} < 0 \rightarrow$ Object slows down as it falls.

Question : What is the critical value?

$$\frac{dv}{dt} = 0$$

$$\Rightarrow 9.8 - \frac{v}{5} = 0 \Rightarrow \boxed{v = 49}$$

critical value

This critical value is called equilibrium solution.

* $v(t) = 49$ is a sol'n to DE (I).

Verify: $\frac{dv}{dt} = 9.8 - \frac{v}{5}$

$$v(t) = 49 \Rightarrow \frac{dv}{dt} = 0 = 9.8 - \frac{49}{5} = 9.8 - 9.8 \quad \checkmark$$

→ Go back to the original equation:

$$* \quad \frac{dv}{dt} = g - \frac{k}{m} v$$

equilibrium
solution $\Rightarrow \frac{dv}{dt} = 0 = g - \frac{k}{m} v$
occurs when

$$\Rightarrow \boxed{v = \frac{mg}{k}} \quad \text{equilibrium sol'n}$$

$$\Rightarrow \underbrace{kv}_{\text{drag}} = \underbrace{mg}_{\text{gravity}}$$

In the context of this question, equilibrium solution corresponds to perfect balance between gravity and drag.

- ③ Checking the slopefield we see all the solution curves are converging to the equilibrium solution.

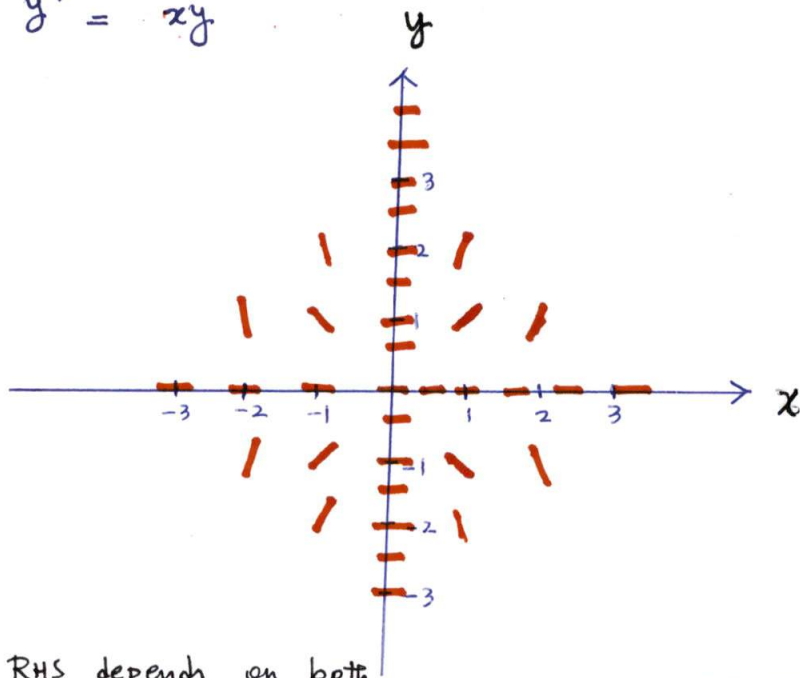
In this context :

equilibrium solution = terminal velocity.
 $= \frac{mg}{K}$

This can be verified from the solution as well:

$$\lim_{t \rightarrow \infty} v(t) = \lim_{t \rightarrow \infty} \frac{mg}{K} + \underbrace{C}_{0} e^{-\frac{K}{m}t} = \frac{mg}{K}$$


Example: $y' = xy$



Since RHS depends on both
 x and y , we should evaluate
 at different x and y
 values.

$$\frac{dy}{dx} = xy$$

$$(0,0) \rightarrow y' = 0$$

$$(0,y) \rightarrow y' = 0 \rightarrow \text{on } y\text{-axis}$$

$$(x,0) \rightarrow y' = 0 \rightarrow \text{on } x\text{-axis}$$

$$(1,1) \rightarrow y' = 1 \leftarrow (-1,-1)$$

$$(1,-1) \rightarrow y' = -1 \leftarrow (-1,1)$$

Side Note: Compare RHS of

$$\frac{dy}{dx} = \underbrace{xy}_{\text{depends on } x \text{ and } y} \text{ and}$$

$$\frac{dv}{dt} = \underbrace{g - \frac{k}{m}v}_{\text{only a function of } v \text{ (dependent var.)}} \quad (\text{dep. \& indep. var.})$$

* More about this in the next class.

Running this process for lots of points, the direction field looks like:

$$\frac{dy}{dx} = xy$$

