

## MATLAB Center :

Hours: Wednesday, Oct 24 : 10 am - 1 pm

Thursday, Oct 25 : 11 am - 2 pm

Friday, Oct 26 : 11 am - 1 pm

## Jordan's Tutorials :

↙  
(Section 102 instructor)

Friday, Oct 26 : 1 - 2 pm

Wednesday, Oct 31 : 1 - 2 pm

Thursday, Nov 1 : 1 - 2 pm

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## 2<sup>nd</sup> order ODEs :

Oct 24  
Lec 21

$$\begin{cases} y'' = f(t, y, y') \\ y(t_0) = y_0 \\ y'(t_0) = \bar{y}_0 \end{cases}$$

2<sup>nd</sup> -order IVP

$y_0$  and  $\bar{y}_0$  are constant numbers.

## 2<sup>nd</sup> order linear ODE

$$y'' + p(t)y' + q(t)y = g(t)$$

if  $g(t) = 0 \rightarrow$  2<sup>nd</sup> order linear homogeneous ODE

2<sup>nd</sup> order linear homogeneous  
with constant coefficient

$$y'' + by' + cy = 0$$

↙ constants ↘

(if  $ay'' + by' + cy = 0$   
divide by  $a$ )

Theorem (Existence & Uniqueness of the linear case)

$$y'' + p(t)y' + q(t)y = g(t) \quad , \quad y(t_0) = y_0 \quad , \quad y'(t_0) = \bar{y}_0$$

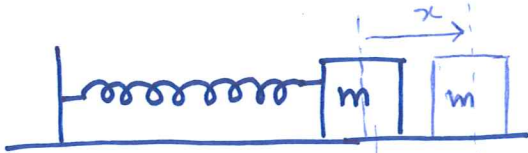
If  $p(t)$ ,  $q(t)$  and  $g(t)$  are continuous on some interval  $I$  containing  $t_0$ , then the equation has exactly one solution,  $y = \phi(t)$ , and  $\phi(t)$  is defined on the same interval  $I$ .

i.e. Interval of existence = Interval of continuity =  $I$ .

Let's see some physical applications of the 2<sup>nd</sup> order ODEs before doing mathematical computation to find the general solution.

### Application of 2<sup>nd</sup> order ODE :

(1) Vibrating Springs (Mass-spring system)



(vertical or horizontal, both work.)

A spring attached to an object with mass  $m$ . Stretch or Compress the spring  $x$  units in length

Hooke's law : The spring exerts a force proportional to the displacement  $x$  and in the opposite direction of the displ.  $x \rightarrow$  Restoring force

Newton's 2<sup>nd</sup> law :  $F = -kx$   
↓  
spring constant ( $k > 0$ )

$$ma = -kx$$

$$a = \frac{d^2x}{dt^2} \Rightarrow m \frac{d^2x}{dt^2} = -kx$$

Undamped equation  $\Rightarrow \boxed{x'' + \frac{k}{m} x = 0} \rightarrow \begin{matrix} 2^{\text{nd}} \text{ order} \\ \text{linear} \end{matrix}$

All external forces such as friction & air resistance are neglected  $\rightarrow$  system called : Undamped motion

↳ Oscillation continuous forever!

Let's consider resisting forces (friction or air resistance)

↳ Oscillation dies off slowly :

↳ This effect is called damping.

Assumption: Damping force is proportional to the velocity of the object & in the opposite direction of  $V$ .

$$\text{damping force} = -cV = -c \frac{dx}{dt}$$

$$F = -kx - c \frac{dx}{dt}$$

$$m \frac{d^2x}{dt^2} = -kx - c \frac{dx}{dt}$$

$$\boxed{\frac{d^2x}{dt^2} + \frac{c}{m} \frac{dx}{dt} + \frac{k}{m} x = 0}$$

→ 2<sup>nd</sup> order linear hom. damped.

Apply some <sup>additional</sup> external force to the system  $F$ :

$$\boxed{\frac{d^2x}{dt^2} + \frac{c}{m} \frac{dx}{dt} + \frac{k}{m} x = \bar{F}(t)}$$

→ 2<sup>nd</sup> order linear non-hom. damped

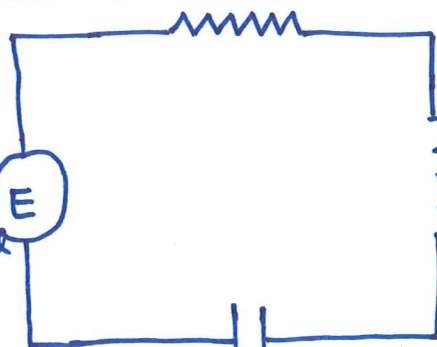
$$\begin{cases} x(0) = x_0 \\ v(0) = v_0 \end{cases}$$

↳ forced 2<sup>nd</sup> order ODE

## (2) The RLC circuit (series)

An electric circuit containing a resistor, an inductor and a capacitor.

resistance :  $R$  → resistor



$I(t)$  : the current in the circuit at time  $t$

$q(t)$  : the charge on the capacitor at time  $t$ .

Facts : •  $I(t) = \frac{dq(t)}{dt} \rightarrow \frac{dI}{dt} = \frac{d^2q}{dt^2}$

- Voltage drops across resistor, inductor and capacitor.

voltage across the inductor  $\leftarrow E_L = L \frac{dI}{dt}$

voltage across the resistor  $\leftarrow E_R = RI$

voltage across the capacitor  $\leftarrow E_C = \frac{1}{C} q(t)$

Kirchhoff's 2<sup>nd</sup> law: Sum of the voltage drop  
= sum of the supplied voltage

$$\Rightarrow E_L + E_R + E_C = E(t)$$

$$\Rightarrow L \frac{dI}{dt} + RI + \frac{1}{C} q(t) = E(t)$$

$$\Rightarrow \boxed{L \frac{d^2 q}{dt^2} + R \frac{dq}{dt} + \frac{1}{C} q(t) = E(t)}$$

↙ 2<sup>nd</sup> order linear ODE

$$\begin{cases} q(0) = q_0 \\ I(0) = I_0 \end{cases}$$

\* Differentiate both sides of the equation above and you'll get an ODE for  $I(t)$ .

2<sup>nd</sup> order constant coefficients:

$$y'' + by' + cy = 0$$

Convert to a 1<sup>st</sup> order system:

$$y = u \Rightarrow y' = u' = v$$

$$y' = v \Rightarrow y'' = v' = -by' - cy = -bv - cu$$

$$\begin{cases} u' = v \\ v' = -cu - bv \end{cases} \Rightarrow \begin{pmatrix} u' \\ v' \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ -c & -b \end{pmatrix} \begin{pmatrix} u \\ v \end{pmatrix}$$

$\begin{matrix} \nearrow y \\ \searrow y' \end{matrix}$

$$\begin{pmatrix} u' \\ v' \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ -c & -b \end{pmatrix} \begin{pmatrix} u \\ v \end{pmatrix} : \text{Solve the system with eigval and eigvec method}$$

$$\det \begin{pmatrix} -r & 1 \\ -c & -b-r \end{pmatrix} = r(r+b) + c = 0$$

$$\Rightarrow \boxed{r^2 + br + c = 0}$$

Compare this to  $y'' + by' + cy = 0$

→ Characteristic equation for a 2nd order of the form

Example :  $y'' + 3y' + 2y = 0$

$$\begin{pmatrix} y' \\ y'' \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ -2 & -3 \end{pmatrix} \begin{pmatrix} y \\ y' \end{pmatrix}$$

characteristic equation  $\rightarrow r^2 + 3r + 2 = 0 \Rightarrow r_1 = -1, r_2 = -2$

$$\Rightarrow r_1 = -1 \Rightarrow \vec{v}_1 = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

$$r_2 = -2 \Rightarrow \vec{v}_2 = \begin{pmatrix} 1 \\ -2 \end{pmatrix}$$

$$\begin{pmatrix} y \\ y' \end{pmatrix} = c_1 \begin{pmatrix} 1 \\ -1 \end{pmatrix} e^{-t} + c_2 \begin{pmatrix} 1 \\ -2 \end{pmatrix} e^{-2t}$$

$$\boxed{\begin{pmatrix} y \\ y' \end{pmatrix} = \begin{pmatrix} c_1 e^{-t} + c_2 e^{-2t} \\ -c_1 e^{-t} - 2c_2 e^{-2t} \end{pmatrix}}$$

Only take the 1<sup>st</sup> component of the solution vector as the solution of the 2<sup>nd</sup> order ODE.

General solution  $\rightarrow y(t) = c_1 e^{-t} + c_2 e^{-2t}$

The 2<sup>nd</sup> component is just the derivative.

In general:

$$y'' + by' + cy = 0$$

$$r^2 + br + c = 0$$

$$\hookrightarrow \text{solve: eigenval } r_{1,2} = -\frac{b}{2} \pm \frac{1}{2}\sqrt{b^2 - 4c}$$

if  $r_1$  and  $r_2$  are real and distinct ( $b^2 - 4c > 0$ )

$$\Rightarrow \boxed{y(t) = c_1 e^{r_1 t} + c_2 e^{r_2 t}}$$

if  $r_{1,2} = \alpha \pm i\beta$  ( $b^2 - 4c < 0$ )

Do the computation with the system form and take the 1st component  $\leftarrow$

$$\Rightarrow \boxed{y(t) = c_1 e^{\alpha t} \cos \beta t + c_2 e^{\alpha t} \sin \beta t}$$

if  $r^2 + br + c = 0$  has a double root  $r$

$\hookrightarrow$  repeated eigenval

$\hookrightarrow$  Defective matrix

$$\Rightarrow \boxed{y(t) = c_1 e^{rt} + c_2 t e^{rt}}$$

$\rightarrow$  Do the computation with the system representation and take the 1st component.

Ex.

$$\begin{cases} y'' + 3y' = 0 \end{cases} \rightarrow r^2 + 3r = 0 \Rightarrow r = 0, -3$$

$$\begin{cases} y(0) = -2 \\ y'(0) = 3 \end{cases} \Rightarrow \boxed{y(t) = c_1 + c_2 e^{-3t}} \Rightarrow y(t) = -1 - e^{-3t}$$

$$y(0) = c_1 + c_2 = -2 \Rightarrow \boxed{c_1 = -2 + 1 = -1}$$

$$y'(t) = -3c_2 e^{-3t} \rightarrow y'(0) = -3c_2 = 3 \Rightarrow \boxed{c_2 = -1}$$