





government subsidizing

public and shared transportation

relative

importance of planning

scale of AV

infrastructure implementation

type, size

and age of urban fabric

modes

Data and

Focused on optimization of AVs and personal navigation

connectivity between transporta-

tion modes

Integration limited to conventional High bus -trains + bikes cars + other

public transit integratio

transportatior

options and trends

of diversi- | Pluralizatio

y in transp. \mid public tra

urban move-ment patterns

FOR P. TRANSIT

Iternatives | alternative

Step 1

Identifying key factors + driving forces in the system

Based on the methods described for scena io learning, the largest possible number of relevant factors and driving forces must be collected through collective brainstorming sections. In TIPSLab, we found nearly 70 key factors that we judged pertinent to the problem of AVs and urban form, across several categories. In the diagram to the right, the different categories are identified by different colors, as follows:

Driving Forces Demographic Social & Lifestyle





Classifying the key factors

All the key factors and driving forces are studied individually and classified based on level of uncertainty (i.e., how certain we are that a certain factor will develop a certain way) and level of impact (i.e., how impactful a certain actor can be). In the diagram to the right, Level of Uncetainty is indicated by fill shade and Level of Impact is indicated by the thickness of the outline, as follows:

Degree of Uncertainty	Level of Impact
Low	High
Medium	Medium
High	Low



Connecting the system

All the factors must be connected in a network of influences. The diagram presents the final network diagram defined by TIPSLab. Strength of connection is defined as follows Connectivity between Forces

Moderate Important



Defining the scenarios' structure

For manageability, we will focus only on two clusters of factors for structuring the scenarios' main variances. They are expected to be very uncertain and very impactful. Because of their uncertainty, at least two opposite behaviours can be defined for each key factor. Finally, the combination of these variations would result in 4 scenarios, a reasonable number for in depth exploration. All the remaining factors should be then considered in relation to the structuring variances in each scenario.

In the network composed by TIPSLab, it was observed that the factor named "emerging consumer demands" occupies an evident central role in the disposition. We titled its cluster "lifestyle forces + market forces". The two opposite outcomes of the cluster were organized under the titles "conservative" and "progressive". The second most relevant cluster identified was named "Regulatory forces + urban environmental forces". This cluster comprises factors that planners and

decision makers can directly act on, and that are of great interest to the developers of this study. The two opposite outcomes of the cluster were organized under the titles "transit oriented investment" and "AV investment".

Supporting information for developing the scenarios

ios are generated through a series of unstructured theme-specific investigations. T stigations preceded the beginning of th nodology itself and continued throughout he entire process. They are the result of expratory conversations taking place in lieu o the data that is currently unavailable regarding AV impact

Here only a few diagramatic figures, summarizing some examples of what was investigated, are presented.



	Dessible small increase offer trade off	
Uptake Very slow due to initial high prices and long fleet turnover periods.	Road space demand Slight decrease in the long term, when uptake reaches relevant percentages.	Sprawl Minimally Incentivized, as trips remain within 45min and speeds do not improve to great effect.
Very slow initially, modest after technology is mature	Reduced demand mainly due to reduced car ownership. Small increase due to large number of vehicles and higher vehicle miles; difference if offset to significant extent in mid to long term because of high AV network efficiency. After ban of manual driving (long term), system efficiency might be able to significantly surpass increase of trips and result in freed road space.	Controlled. Typical suburban developments are disadvantageous due to limited service areas for transit systems. However, affluent AV oriented suburbs emerge around the possibility of longer commutes (e.g. through mobile offices).
Vehicle technology Slow progress through L3 to L4, with mixed fleet in the long term. Vehicles follow conventional car archetype, with option of manual driving.	Transportation of goods Mostly manual for local distribution due to high prices and immature infrastructure. Mostly autonomous for long freights in mid-term. Image: Constructure infrastructure	Parking Parking infrastructure remain mostly unaltered.
Slow progress through L3 to L4, with mixed fleet in the long term. Market is open to new AV models, such as individual pods and inhabitable modules (e.g. mobile offices), but these are mostly restricted to the wealthy due to noncompetitive prices compared to alternatives. In the long term, vehicle and system designs that allow for seamless connectivity to the transit system become popular.	Slow transition to automated systems.	Further reduction of surface parking, need for AV-specific car sharing/ AV transit pods parking.
Number of vehicle No significant difference.	Legislation Little AV interference	 AV infrastructure Intelligence in busy intersections and in a few (self-funded) affluent communities. Rare dedicated lanes in highways
Modest decrease, assuming AV sharing services and reinforcement of transit systems reduce overall car ownership.	Late incentive to autonomous car sharing and AV inclusion in public transit systems, but little support for personal AVs in general.	 Intermodal structures & intelligence Dedicated lanes only for transit-related AVs AV oriented buildings, such as hubs for mobile inhabitable modules, fully unmanned "drive-thru" services, and others.
Vehicle miles Increase for AVs and small overall increase for the entire automobile fleet in the long term, when uptake reaches relevant percentages (<8%). Increase is due to "zombie" trips, convenience of trips, and wider range of users otherwise unable to drive.	Transit infrastructure Increased network and service. \mathcal{FF} \mathcal{FF} Decreased network and service. Average income of transit riders decrease.	Other infrastructural changes No significant changes
Small increase, as car commutes are relatively low and only a small percentage of these would use AVs. Car-sharing would also increase vehicle miles through "zombie" rides.	In the long term, transit systems becomes diversified and better con- nected, assisted by autonomous technologies.	- Possibility of using freed road space for bicycle lanes, parks, urban agriculture, etc.

CONTEXT

(b)

ROS JRF S() ;FNAF

EACH CLUSTER IS **IDERED TO HAVE TW** 4 POSSIBLE FUTURE SCENAP OS (FIGURE ON RIGH





INFORMING THE SCENARIOS TO FURTHER DETAIL

Studying coherent sets of assumptions

Considering the set of driving forces systematically laid out in steps 1 to 3, and considering the crossing of possible outcomes for key forces (step 4), four different scenarios could be outlined. The table below describe the overall contexts that define the scenarios.

Based on these contexts and the assumed outcomes of the key driving forces being con sidered, several more specific assumptions could also be studied. Since the purpose o this research is speculating on the possible impact of AVs on future cities, a few specific assumptions are crucial in coherently populating future scenarios and understanding AV impact on urban form and quality.

The series of diagrams and descriptions below describe these assumptions for each scenario. The assumptions are grouped in the following topics: AV uptake, vehicle technology, number of vehicles, vehicle miles, road space demand, transportation of goods, legislation, sprawl, parking, transit infrastructure AV infrastructure and other infrastructural changes.

In a next step of the present research, these assumptions can be inputed in predictive models, further informing how different approaches to AV and planning may impact our cities.



ASSUMPTIONS PER SCENARIO

CLUSTER B ry forces + urban environmental forces

POSSIBLE OUTCOME W INTERVENTION FOR PUBLIC TRANSPORTATION

iptake progress very slowly (m o focus on public transit to reduce n, pollution and accidents. Va y and connectivity of public transit is rded by users' conservative needs expectations; this includes AV inteion in public transit systems, which tes a relaively long time to be consi ed. No drastic changes to fleet comp ion and infrastructure is expected in e mid to long tern

> sit to reduce congestion, pollution d accidents, giving little immediate atn to AVs. In time, a robust public sit system supports the success of AV

naring services as alternatives to car rship. In the long term, autonom sportation (e.g. buses) and inc ual pods are gradually incorporated in e public transit network.

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POSSIBLE OUTCOME Z INTERVENTION FOR AUTONOMUS VEHICLES

l 4 AV uptake happens at rela ated pace, as favorable inc tion and planning (e.g. subs. ated Ianes) make AVs a co e option, thus boosting uptake nute related habits are similar to t 's. Car sharing services take the

ket share of taxis, with small relative vth. Popular vehicles typology rema nilar to non-autonomous models and tion of manual driving is protected b

lic demand.

Level 4 AV uptake happens at most ad elerated pace, as favorable incentives meet fast changing and progressive needs and demands. Different compahies and vehicle models appear in the narket, offering a diversity of services, eatures and even roles for personally owned AVs. A variety of ownership

models exist. Vehicles that function as office space or sleeping space, among others, are common, and commute habits